

Freescale Kinetis Basic

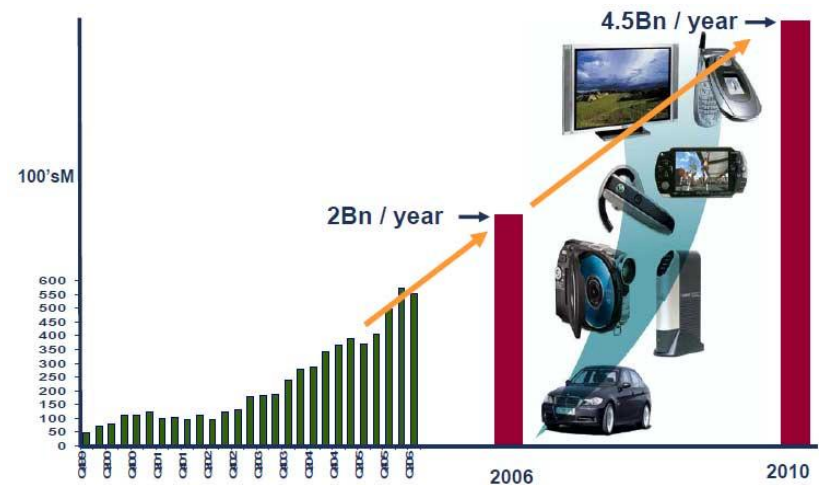
清华Freescale应用开发研究中心 曾鸣

2012年03月



ARM History

- ARM delivered ARM6 in 1991
 - Introduced 32 bit addressing support
 - New instruction for program status registers
 - Variant used in Apple Newton PDA
- By 1996 ARM7 was being widely used
 - Microsoft started port of WinCE to ARM
 - Added multimedia extensions
- Exponential growth from then on...



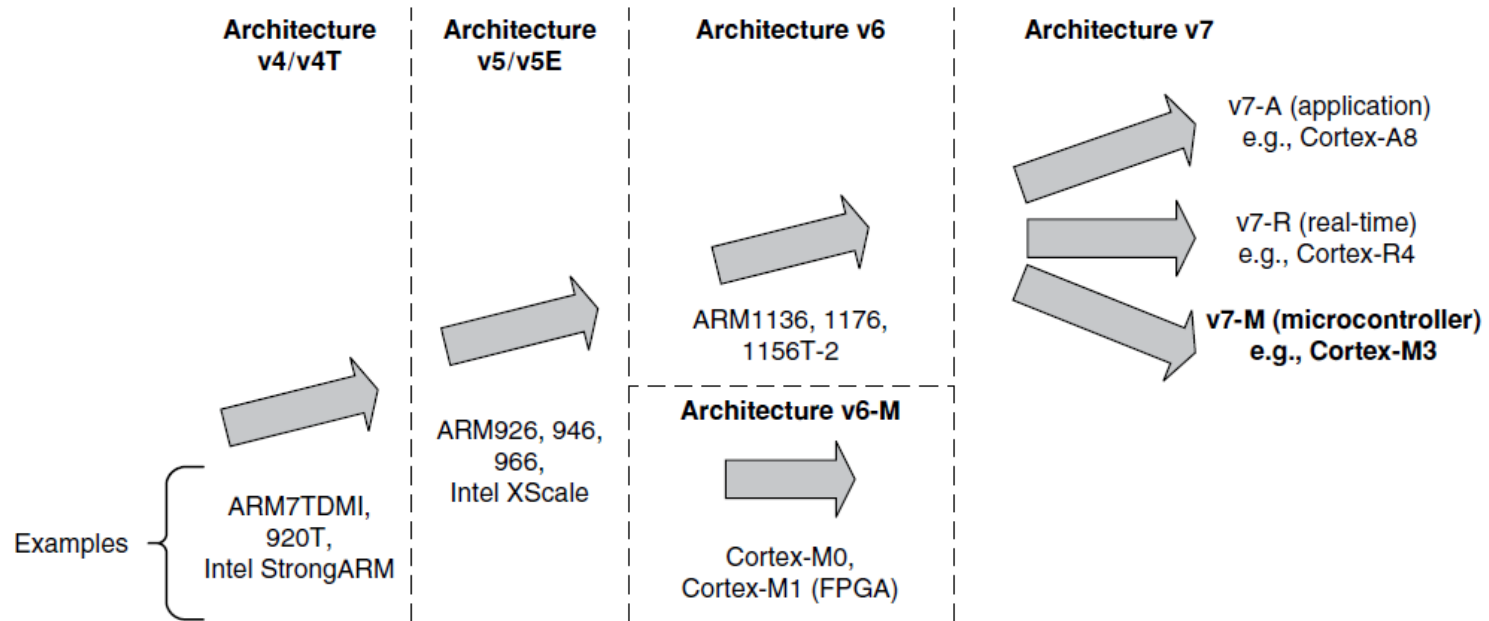


Thousands of Physical IP Users



ARM架构进化史

ARM的发展过程



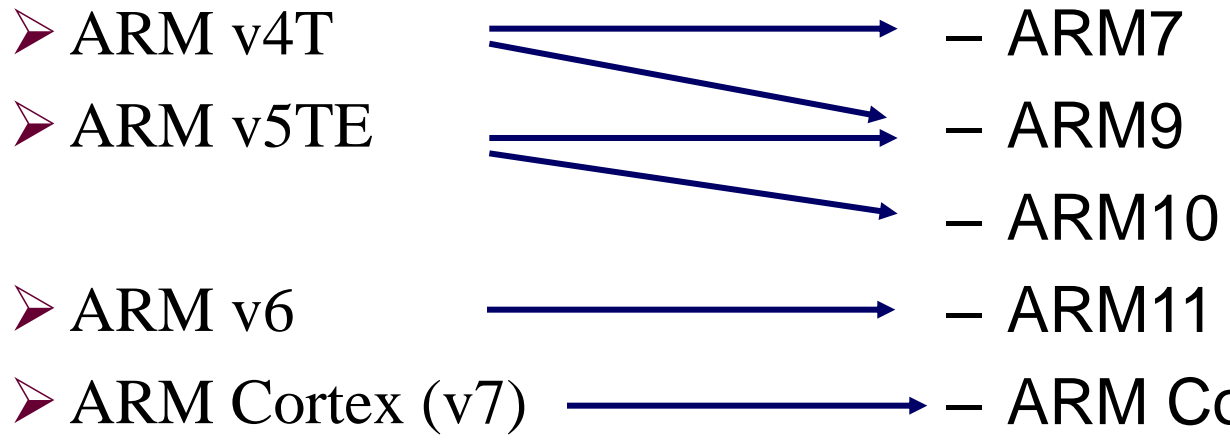
The Evolution of ARM Processor Architecture.

ARM公司只做CPU设计，采用出售IP的方式运营，半导体制造商无需自己设计CPU，是生产关系的革命，提高了生产力

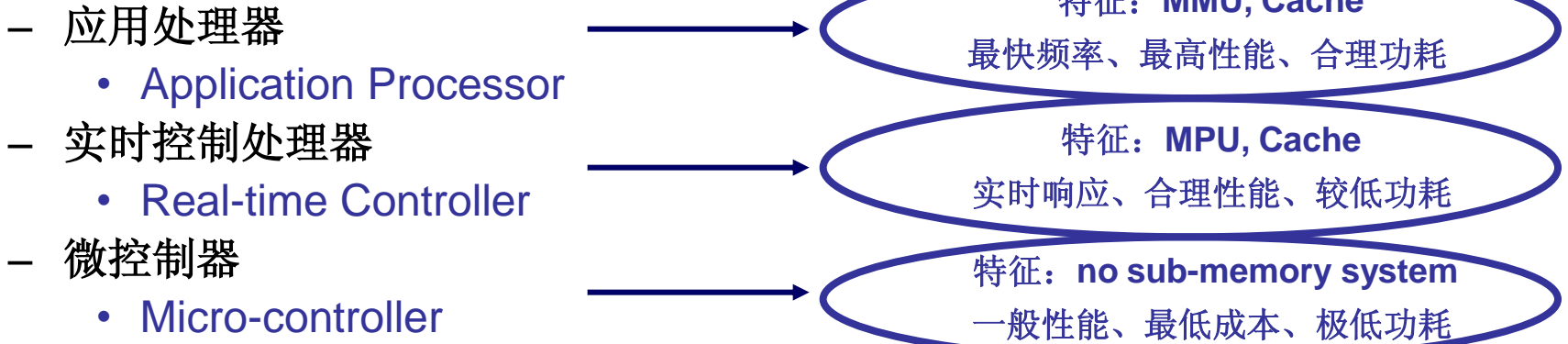


ARM处理器的分类

■ 结构体系版本 (Architecture) • Processor Family



• 按应用特征分类

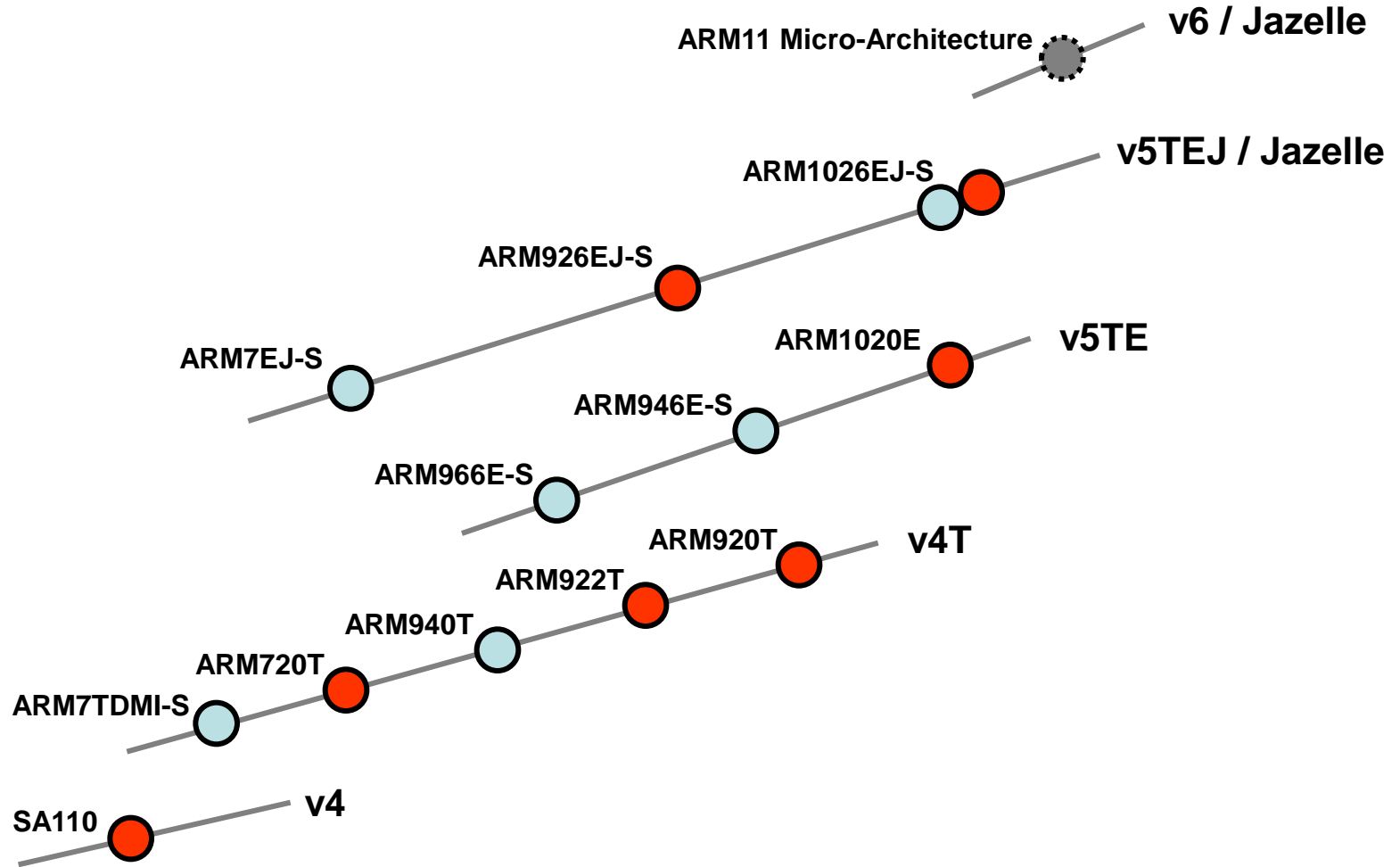


ARM and StrongARM

- Intel gained certain IP from ARM as part of lawsuit settlement and modified ARM architecture branding it as StrongARM
- StrongARM name was changed to XScale
 - Processor SA1000 , SA1100
- XScale is close to ARMv5 instruction set
- XScale division of Intel was sold to Marvel Inc. in 2006



Roadmap of ARM V4/V5/V6



ARM V4

- ARMV4是目前支持的最老的架构,是基于32-bit地址空间的32-bit指令集。ARMv4除了支持ARMv3的指令外还扩展了：
 - ❖ **支持halfword的存取**
 - ❖ **支持byte和halfword的符号扩展读**
 - ❖ **支持Thumb指令**
 - ❖ **提供Thumb和Normal状态的转换指令**
 - ❖ **进一步的明确了会引起Undefined异常的指令**
 - ❖ **对以前的26bits体系结构的CPU不再兼容**



ARMv4T

- ARMv4T增加了**16-bit Thumb** 指令集，这样使得编译器能产生紧凑代码（相对于32-bit代码，内存能节省到35%以上）并保持32-bit系统的好处。
- Thumb在处理器中仍然要扩展为标准的32位ARM指令来运行。用户采用16位Thumb指令集最大的好处就是可以获得更高的代码密度和降低功耗。



ARM V5TE

- 1999年推出ARMv5TE其**增强了Thumb体系**,增强的Thumb体系增加了一个新的指令同时改进了Thumb/ARM相互作用、编译能力和混合及匹配ARM与Thumb例程, **以更好地平衡代码空间和性能**
- 并在ARM ISA上扩展了**增强的DSP 指令集**:
增强的DSP指令包括支持饱和算术 (saturated arithmetic), 并且针对Audio DSP应用提高了70%性能。 'E'扩展表示在通用的CPU上提供DSP能力。



ARMv5TEJ

- 2000年推出ARMv5TEJ，增加了Jazelle扩展以支持Java加速技术。
- Jazelle技术比仅仅基于软件的JVM性能提高近8倍的性能减少了80%的功耗。



ARMv6

- 2001年推出ARMv6，它在许多方面做了改进如内存系统、异常处理和较好地支持多处理器。
- SIMD扩展使得广大的软件应用如Video和Audio codec的性能提高了4倍。
- Thumb-2和TrustZone 技术也用于ARMv6中。ARMv6第一个实现是2002年春推出的ARM1136J(F)-STM处理器，2003年又推出了ARM1156T2(F)-S和ARM1176JZ(F)-S处理器。



ARMv7

- ARMv7定义了3种不同的处理器配置（ processor profiles ）：
 - **Profile A**是面向复杂、基于虚拟内存的OS和应用的
 - **Profile R**是针对实时系统的
 - **Profile M**是针对低成本应用的优化的微控制器的。
- 所有ARMv7 profiles实现**Thumb-2**技术，同时还包括了**NEON™**技术的扩展提高DSP和多媒体处理吞吐量400% ，并提供**浮点支持**以满足下一代3D图形和游戏以及传统嵌入式控制应用的需要。



系列	相应产品	性能特点
ARM7 系列	ARM7TDMI , ARM7TDMI-S , ARM720T, ARM7EJ	三级流水 性能: 0.9MIPS/MHz, 可达到130MIPs (Dhrystone2.1)
ARM9 系列	ARM920T, ARM922T	五级流水, 性能: 1.1MIPS/MHz, 可达300 MIPS (Dhrystone 2.1), 单32-bit AMBA bus 接口, 支持MMU
ARM9E 系列	ARM926EJ-S, RM946E-S, ARM966E-S, ARM968E-S, ARM996HS	五级流水, 支持DSP指令。 性能: 1.1MIPS/MHz, 可达300 MIPS (Dhrystone 2.1), 高性能AHB, 软核 (soft IP)
ARM10 系列	ARM1020E, ARM1022E ARM1026EJ-S	6级流水支持分支预测 (branch prediction), 支持DSP指令。 性能: 1.35 MIPS/MHz, 可达 430+ Dhrystone 2.1 MIPS, , 可选支 持高性能浮点操作, 双64位总线接口, 内部64位数据通路



系列	相应产品	性能特点
ARM11 系列	ARM11MPCore, ARM1136J(F)-S, ARM1156T2(F)-S, ARM1176JZ(F)-S	<p>8级流水线(9级ARM1156T2(F)-S), 独立的load-store和arithmetic流水线, 支持分支预测和返回栈 (Return Stack)。强大的ARMv6指令集, 支持DSP, SIMD (Single Instruction Multiple Data) 扩展, 支持ARM TrustZone、Thumb-2核心技术。740 Dhrystone 2.1 MIPS, 低功耗0.6mW/MHz (0.13μm, 1.2V)</p>
Cortex 系列	Cortex-A8, Cortex-M3, Cortex-R4	<p>Cortex-A系列: 面向用于复杂OS和应用的的应用处理器 (applications processors), 支持ARM, Thumb and Thumb-2指令集。 Cortex-R系列: 面向嵌入式实时领域的嵌入式处理器, 支持ARM, Thumb,和Thumb-2指令集。 Cortex-M系列: 面向深嵌入式价格敏感的嵌入式处理器, 只支持Thumb-2指令集</p>



ARM Design Philosophy

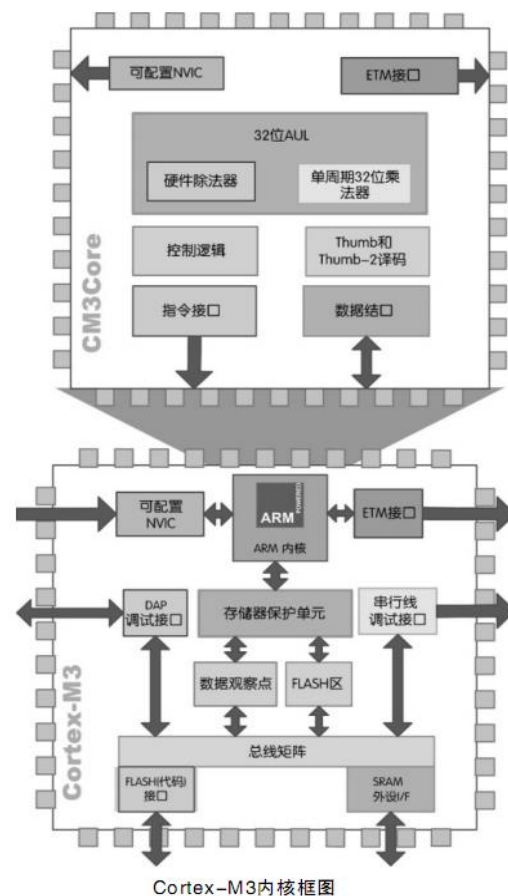
- ARM core uses RISC architecture
 - Reduced instruction set
 - Load store architecture
 - Large number of general purpose registers
 - Parallel executions with pipelines
- But some differences from RISC
 - Enhanced instructions for
 - Thumb mode
 - DSP instructions
 - Conditional execution instruction
 - 32 bit barrel shifter



Cortex-M3/4内核主要是应用于低成本、小管脚数和低功耗的场合，并且具有极高的运算能力和极强的中断响应能力。

Cortex-M3/4处理器采用纯Thumb2指令的执行方式，使得这个具有32位高性能的ARM内核能够实现8位和16位的代码存储密度。ARM Cortex-M3/4处理器是使用最少门数的ARM CPU，核心门数只有33K，在包含了必要的外设之后的门数也只有60K，使得封装更为小型，成本更加低廉。

Cortex-M3/4采用了ARM V7哈佛架构，具有带分支预测的3级流水线，中断延迟最大只有12个时钟周期，在末尾连锁的时候只需要6个时钟周期。同时具有**1.25DMIPS/MHZ**的性能和**0.19mW/MHZ**的功耗。



Cortex-M3/4内核：哈佛架构

Cortex-M3/4 中央内核基于哈佛架构，指令和数据各使用一条总线。

与 Cortex-M3/4不同，ARM7 系列处理器使用冯诺依曼（Von Neumann）架构，指令和数据共用信号总线以及存储器。

由于指令和数据可以从存储器中同时读取，所以 Cortex-M3/4 处理器对多个操作并行执行，加快了应用程序的执行速度。

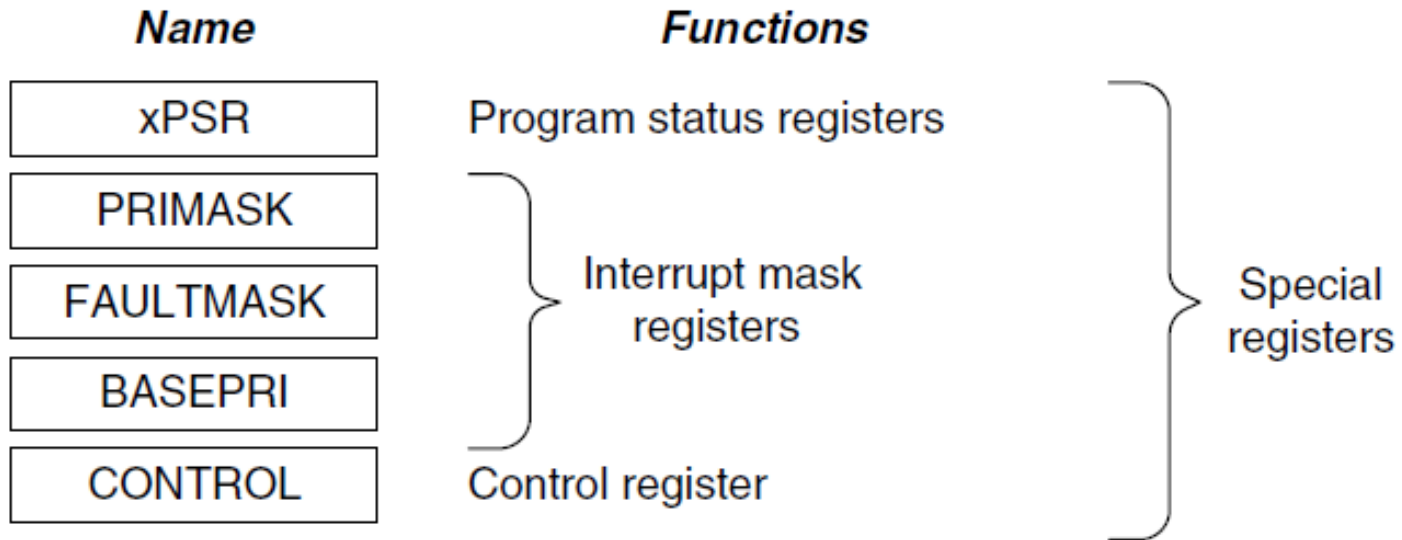


Cortex-M3/4内核：寄存器组

<i>Name</i>	<i>Functions (and banked registers)</i>	
R0	General-purpose register	Low registers
R1	General-purpose register	
R2	General-purpose register	
R3	General-purpose register	
R4	General-purpose register	
R5	General-purpose register	
R6	General-purpose register	
R7	General-purpose register	
R8	General-purpose register	High registers
R9	General-purpose register	
R10	General-purpose register	
R11	General-purpose register	
R12	General-purpose register	
R13 (MSP)	R13 (PSP) Main Stack Pointer (MSP), Process Stack Pointer (PSP)	
R14	Link Register (LR)	
R15	Program Counter (PC)	



Cortex-M3/4内核：特殊功能寄存器

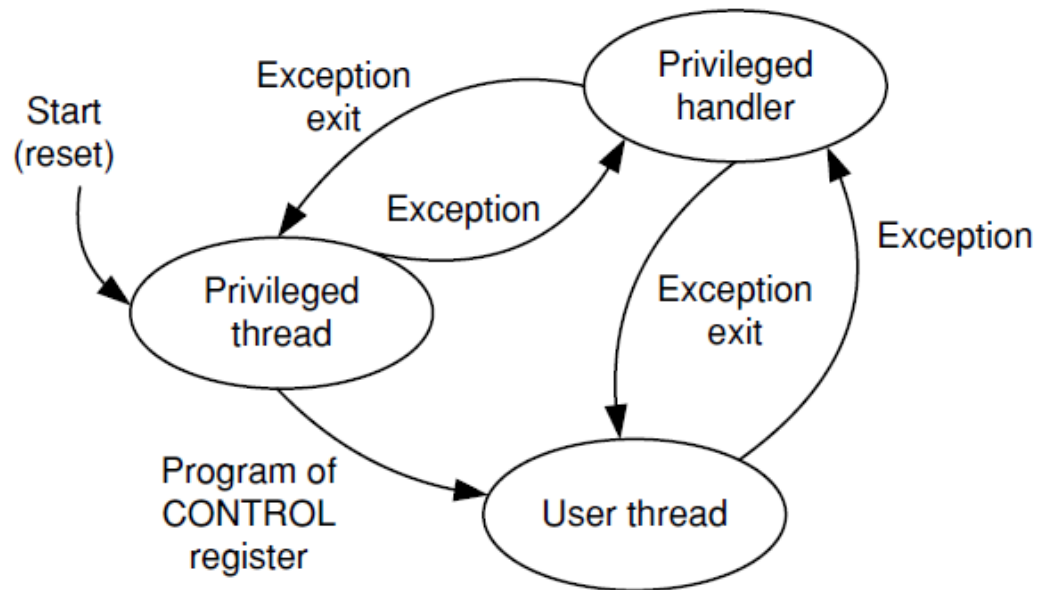


Cortex-M3/4内核：特权态和用户态

When running an exception handler

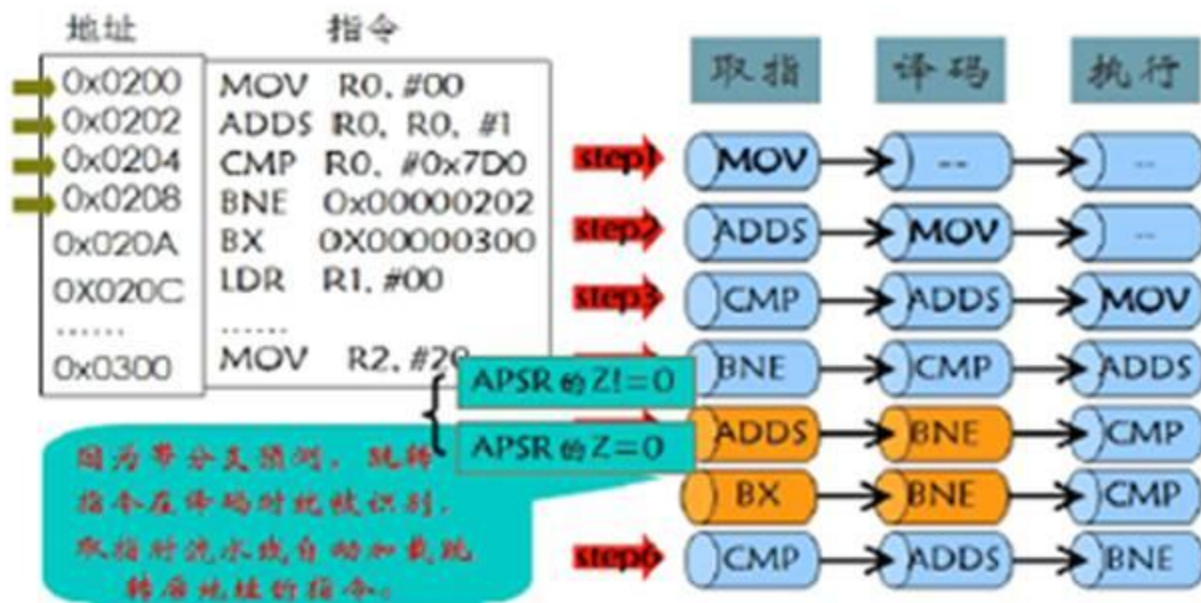
When not running an exception handler (e.g., main program)

<i>Privileged</i>	<i>User</i>
Handler mode	
Thread mode	Thread mode



Cortex-M3/4内核：分支预测的流水线

内核流水线分3个阶段：**取指**、**译码**和**执行**。当遇到分支指令时，译码阶段也包含预测的指令取指，这提高了执行的速度。处理器在译码阶段期间自行对分支目的地指令进行取指。在稍后的执行过程中，处理完分支指令后便知道下一条要执行的指令。如果分支不跳转，那么紧跟着的下一条指令随时可供使用。如果分支跳转，那么在跳转的同时分支指令可供使用，空闲时间限制为一个周期。



Cortex-M3/4存储器映射

Cortex-M3/4 处理器采用单一存储映射的模式，提供4GB的可寻址存储空间。

同时，这些空间为代码（代码空间）、SRAM（存储空间），外部存储器/器件和内部/外部外设提供预定义的专用地址。另外，还有一个特殊区域专门供厂家使用。

借助位带操作（bit-banding）技术，Cortex-M3/4 处理器可以在简单系统中直接对数据的单个位进行访问。

存储器映射包含两个位于SRAM的大小均为1MB的bit-band区域和映射到32MB别名区域的外设空间。在别名区域中，某个地址上的加载/存储操作将直接转化为对被该地址别名的位的操作。对别名区域中的某个地址进行写操作，如果使其最低有效位置位，那么bit-band位为 1，如果使其最低有效位清零，那么bit-band位为零。读别名后的地址将直接返回适当的bit-band位中的值。

除此之外，位带操作（bit-banding）为原子位操作，其他总线活动不能对其中断。

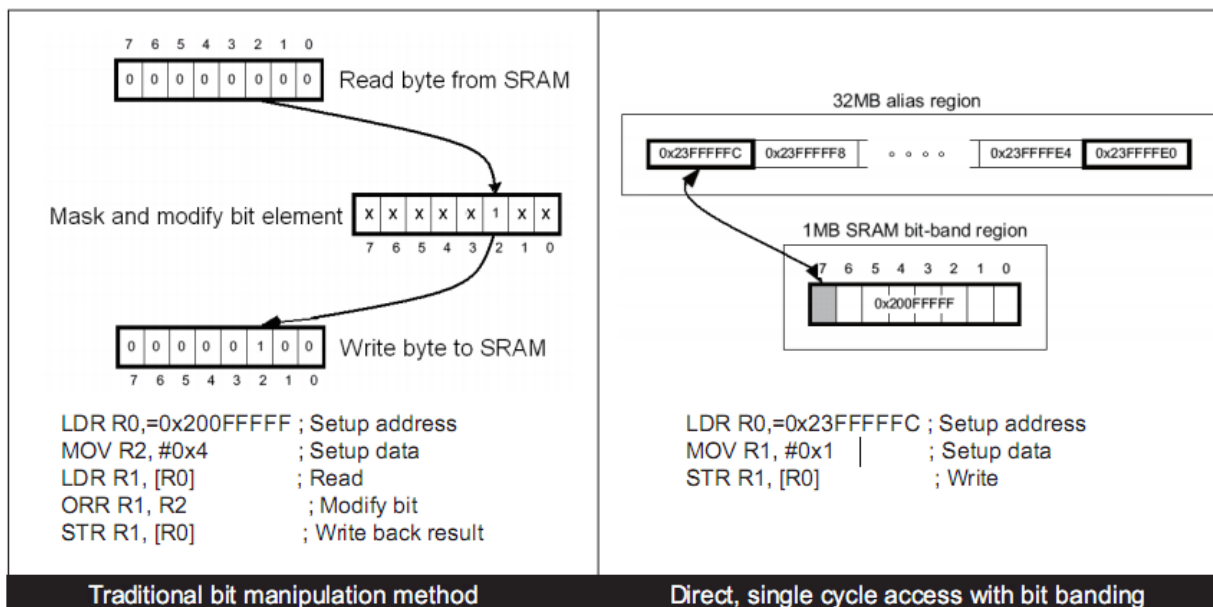


Cortex-M3/4存储器映射

0xFFFFFFFF	System level	Private peripherals including build-in interrupt controller (NVIC), MPU control registers, and debug components
0xE0000000		
0xDFFFFFFF	External device	Mainly used as external peripherals
0xA0000000		
0x9FFFFFFF	External RAM	Mainly used as external memory
0x60000000		
0x5FFFFFFF	Peripherals	Mainly used as peripherals
0x40000000		
0x3FFFFFFF	SRAM	Mainly used as static RAM
0x20000000		
0x1FFFFFFF	CODE	Mainly used for program code. Also provides exception vector table after power up
0x00000000		



Cortex-M3/4的非对齐数据访问和bit-banding



“传统的位处理方法和 Cortex-M3 bit-banding 的比较”

此外，基于传统ARM7 处理器的系统只支持访问对齐的数据，只有沿着对齐的字边界才可以对数据进行访问和存储。Cortex-M3处理器采用非对齐数据访问方式，使非对齐数据可以在单核访问中进行传输。当使用非对齐传输时，这些传输将转换为多个对齐传输，但这一过程不为程序员所见。



嵌套向量中断控制器（NVIC）

NVIC 是 Cortex-M3/4 处理器中一个完整的部分。

NVIC最多可支持 240 个外部中断，每个外部中断最多可具有 256 个可重新动态划分的不同优先级别。它支持优先级别中断源和脉冲中断源。当进入中断时，处理器状态会自动保存在硬盘中，NVIC还支持末尾连锁技术

Cortex-M3/4 处理器使用一个可以重复定位的向量表，表中包含了将要执行的函数的地址，可供具体的中断处理器使用。中断被接受之后，处理器通过指令总线接口从向量表中获取地址。向量表复位时指向零，编程控制寄存器可以使向量表重新定位。



嵌套向量中断控制器 (NVIC)

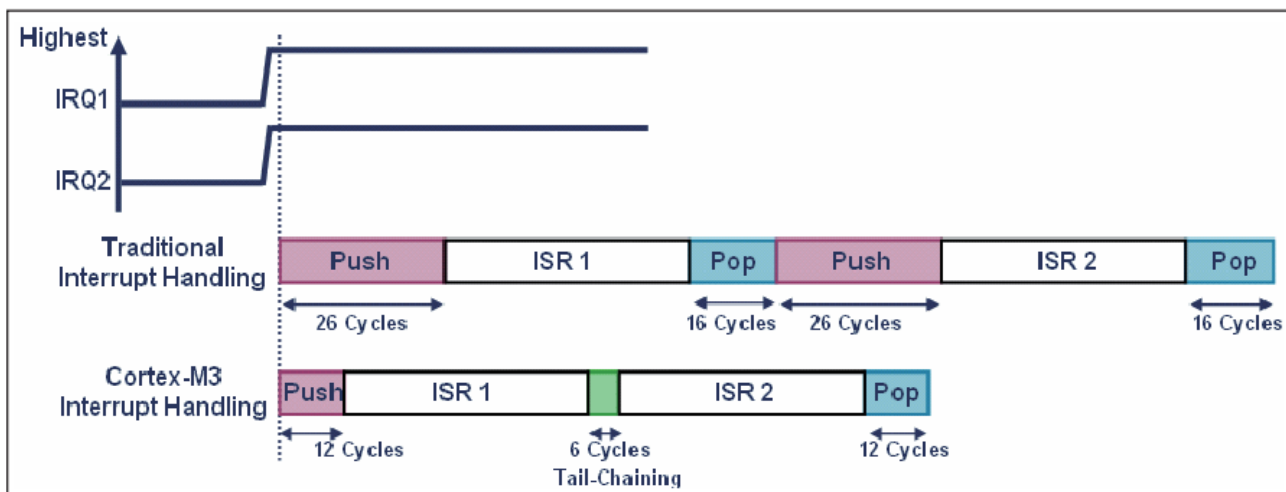
Exception Number	Exception Type	Priority (Default to 0 if Programmable)	Description
0	NA	NA	No exception running
1	Reset	-3 (Highest)	Reset
2	NMI	-2	NMI (external NMI input)
3	Hard fault	-1	All fault conditions, if the corresponding fault handler is not enabled
4	MemManage fault	Programmable	Memory management fault; MPU violation or access to illegal locations
5	Bus fault	Programmable	Bus error (prefetch abort or data abort)
6	Usage fault	Programmable	Program error
7-10	Reserved	NA	Reserved
11	SVCall	Programmable	Supervisor call
12	Debug monitor	Programmable	Debug monitor (break points, watchpoints, or external debug request)
13	Reserved	NA	Reserved
14	PendSV	Programmable	Pendable request for system service
15	SYSTICK	Programmable	System tick timer
16	IRQ #0	Programmable	External interrupt #0
17	IRQ #1	Programmable	External interrupt #1
...
255	IRQ #239	Programmable	External interrupt #239



嵌套向量中断控制器（NVIC）：

可以在硬件中处理堆栈操作，Cortex-M3处理器免去了在传统的 C语言中断服务程序中为了完成堆栈处理所要编写的汇编程序包，这使应用程序的开发变得更加简单。

Cortex-M3/4 处理器使用末尾连锁 (tail-chaining) 技术简化了激活的和未决的中断之间的移动。末尾连锁技术把需要用时 30 个时钟周期才能完成的连续的堆栈弹出和压入操作替换为6个周期就能完成的指令取指，实现了延迟的降低。处理器状态在进入中断时自动保存，在中断退出时自动恢复，比软件执行用时更少，大大提高了频率为 100MHz 的子系统的性能。



▲ 图7 NVIC中的末尾连锁(Tail chaining)技术



Cortex-M支持的Thumb-2指令：

ARM公司在其Cortex-M内核中嵌入新的Thumb-2指令集。新的Thumb-2内核技术保留了紧凑代码质量并与现有ARM方案的代码兼容性，提供改进的性能和能量效率。

Thumb-2是一种新型混合指令集，融合了16位和32位指令，用于实现密度和性能的最佳平衡。在不对性能进行折中的情况下，节省许多高集成度系统级设计的总体存储成本。

Cortex-M支持的Thumb-2指令

目标：看到一段汇编的代码时，会去查处相关的指令集，读懂代码的意图/作用即可。



Thumb-2指令的优势

- 免去 Thumb和ARM代码的互相切换，对于早期的处理器来说，这种状态切换会降低性能。
- Thumb-2指令集的设计是专门面向C语言的，且包括If/Then结构（预测接下来的四条语句的条件执行）、硬件除法以及本地位域操作。（复位向量有堆栈MSP初值。。。）
- Thumb-2指令集提供CLZ、RBIT指令，计算前导零指令和位反转指令，组合使用很强大
- Thumb-2指令集提供SEV、WFE、WFI指令，发送事件、等待事件、等待中断指令，多核任务同步



Cortex-M 的调试

Cortex-M处理器不再直接提供JTAG接口，而是提供一个DAP调试访问接口，在实际芯片中，可以连接不同的DP调试端口设备，实现包括传统JTAG到串行线的各种调试方式，因而支持多种开发工具：



仿真器



调试器



JTAG调试器



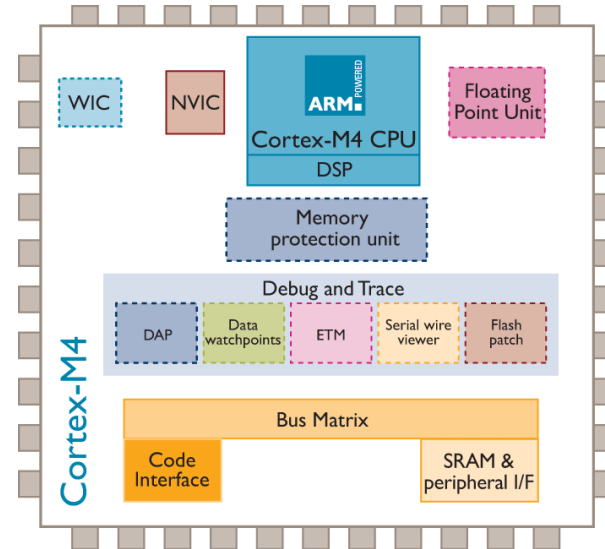
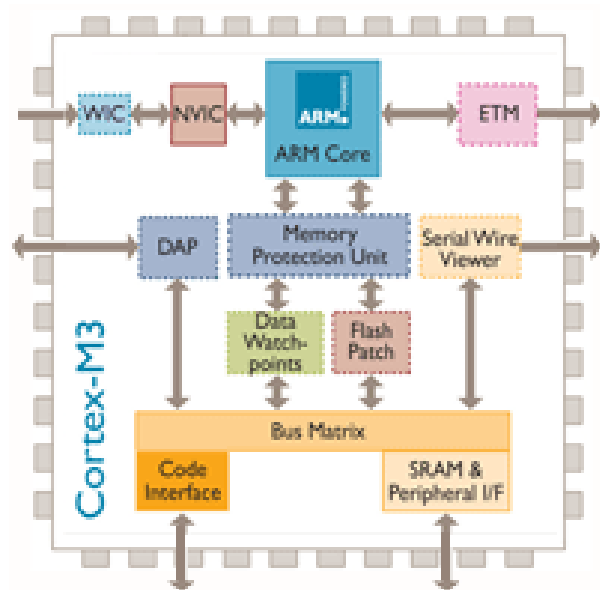
调试器



编程器



ARM Cortex M3 to M4



The Cortex-M4 features a single-cycle multiply-accumulate (MAC) unit, optimized single instruction multiple data (SIMD) instructions, saturating arithmetic instructions and an optional single precision Floating-Point Unit (FPU).

ARM7 vs Cortex-M3

特性	ARM7TDMI-S	Cortex-M3
架构	ARMv4T (冯·诺依曼)	ARMv7-M (哈佛)
ISA 支持	Thumb / ARM	Thumb / Thumb-2
流水线	3 级	3 级+分支预测
中断	FIQ / IRQ	NMI + 1 到 240 个物理中断
中断延迟	24-42 个时钟周期	12 个时钟周期
休眠模式	无	集成
内存保护	无	8 区域内存保护单元
Dhrystone	0.95 DMIPS/MHz (ARM 模式)	1.25 DMIPS/MHz
功耗	0.28mW/MHz	0.19mW/MHz
面积	0.62mm ² (仅内核)	0.86mm ² (内核+外设)*

* 不包含可选系统外设 (MPU和ETM) 或者集成的部件

▲ 表 1-1 ARM7TDMI-S和Cortex-M3比较 (采用100MHz频率和TSMC 0.18G工艺)






学习掌握 ARM Cortex 的思路

■ 自下而上与自上而下

- 8位MCU教学使用传统自下而上的思路
 - CPU寄存器、指令集、汇编、C.....
- ARM发展到Cortex，相当于从微机到小型机，其CPU设计借鉴了PowerPC、MIPS等面向带多用户操作系统的理念，对其指令集、运行模式等的理解需RTOS方面的知识，如优先级、共享资源、竞争、信号量等
 - 应采用自上而下的思路学习，不妨先介绍一些RTOS方面的基本知识，从掌握开发工具的使用开始，读懂CW中自带的范例程序到自己写C程序，自上而下、循序渐进地理解Cortex



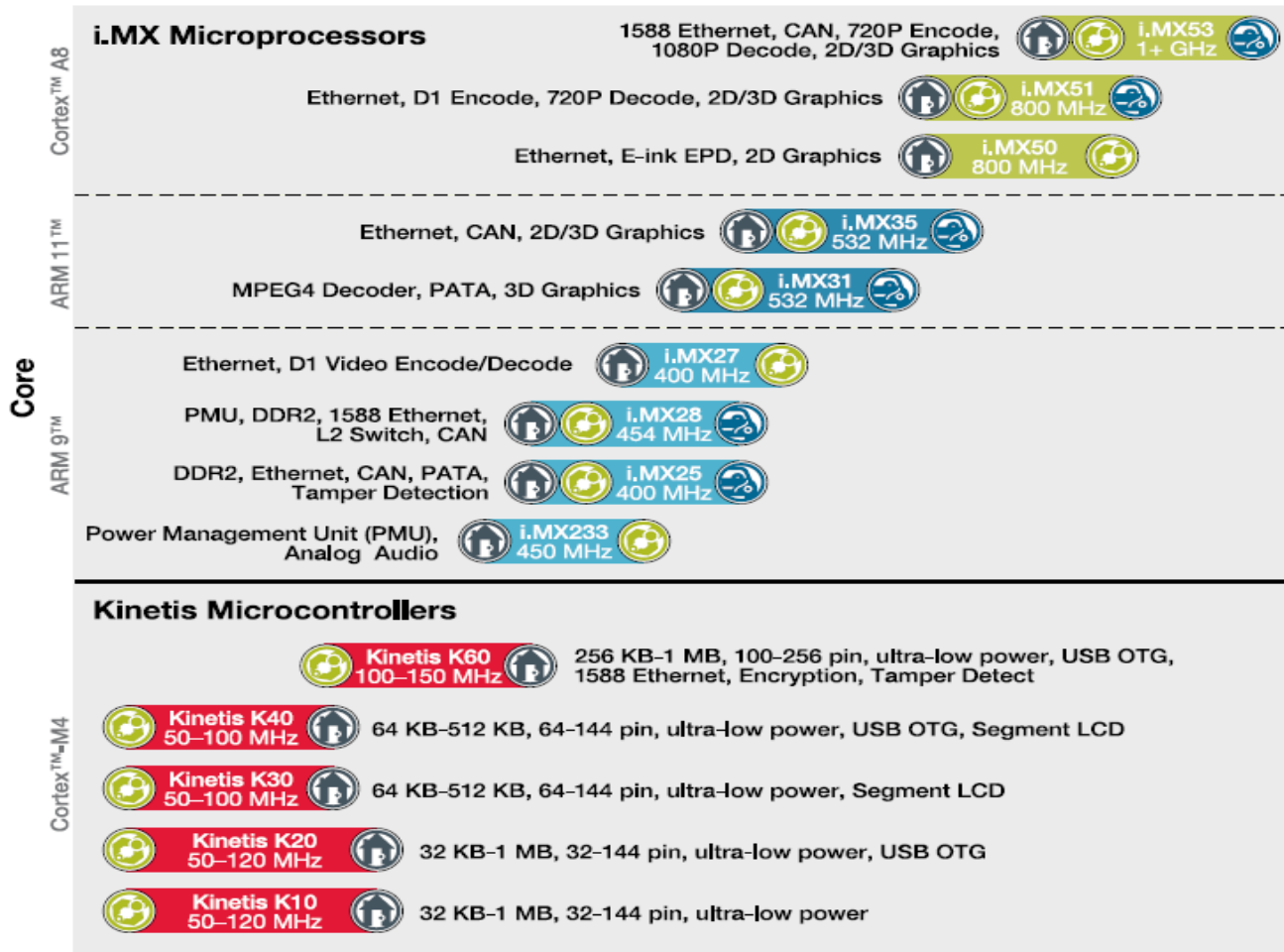
Freescale MCU

32-bit	<i>Built on... Power Architecture® Technology</i>	 90nm	100-400+ MIPS	Market-leading performance, reliability and software enablement for automotive and industrial applications.
	ColdFire ColdFire+	 NEW! 90nm	50-200 MIPS	Application-oriented ultra-low power solutions with optimized enablement, integration and cost for appliance, metering and consumer applications.
	<i>Kinetis based on ARM® Cortex™-M4 core</i>	 NEW! 90nm	50-200 MIPS	Scalable, ultra-low-power product families with bundled software enablement for industrial and consumer applications.
16-bit	Digital Signal Controllers S12 and S12X			Application-oriented solutions for automotive, motor control and power conversion applications.
8-bit	RS08 and S08			Scalable cost & power-optimized product families for industrial, automotive and consumer applications.

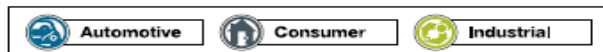


Freescale ARM

Freescale Solutions Based on ARM Technology



Performance



Freescal Kinetic

Kinetis

Design Potential. Realized.



- **Scalability** – Over 200 hardware and software compatible ARM® Cortex™-M4 MCUs with multiple low-power, connectivity, communications, HMI and security features
 - ✓ “DSP” your design - increase performance and reduce power with no added cost
 - ✓ Grow/cost reduce your design with easy migration within/across MCU families
- **Mixed-Signal** – Huge integration with fast 16-bit ADCs, DACs, PGAs and more
 - ✓ Powerful, cost-effective signal conversion, conditioning and control capability
- **90nm Technology** – Low-power Thin-Film Storage Flash with innovative FlexMemory
 - ✓ Robust, efficient flash memory - maximum on-chip feature integration
 - ✓ EEPROM (on-chip!) with unmatched speed, endurance and flexibility
- **Enablement** – Free CodeWarrior IDE with Processor Expert and MQX RTOS. Large 3rd party tool chain support from IAR, KEIL and other ARM ecosystem providers
 - ✓ Free Processor Expert creates application drivers easily and efficiently
 - ✓ Free MQX RTOS creates stable, upgradeable application code with low/no –cost file system, graphics, connectivity and security plug-ins
 - ✓ Reduce integration effort, development cost and time-to-market



Kinetis 系列

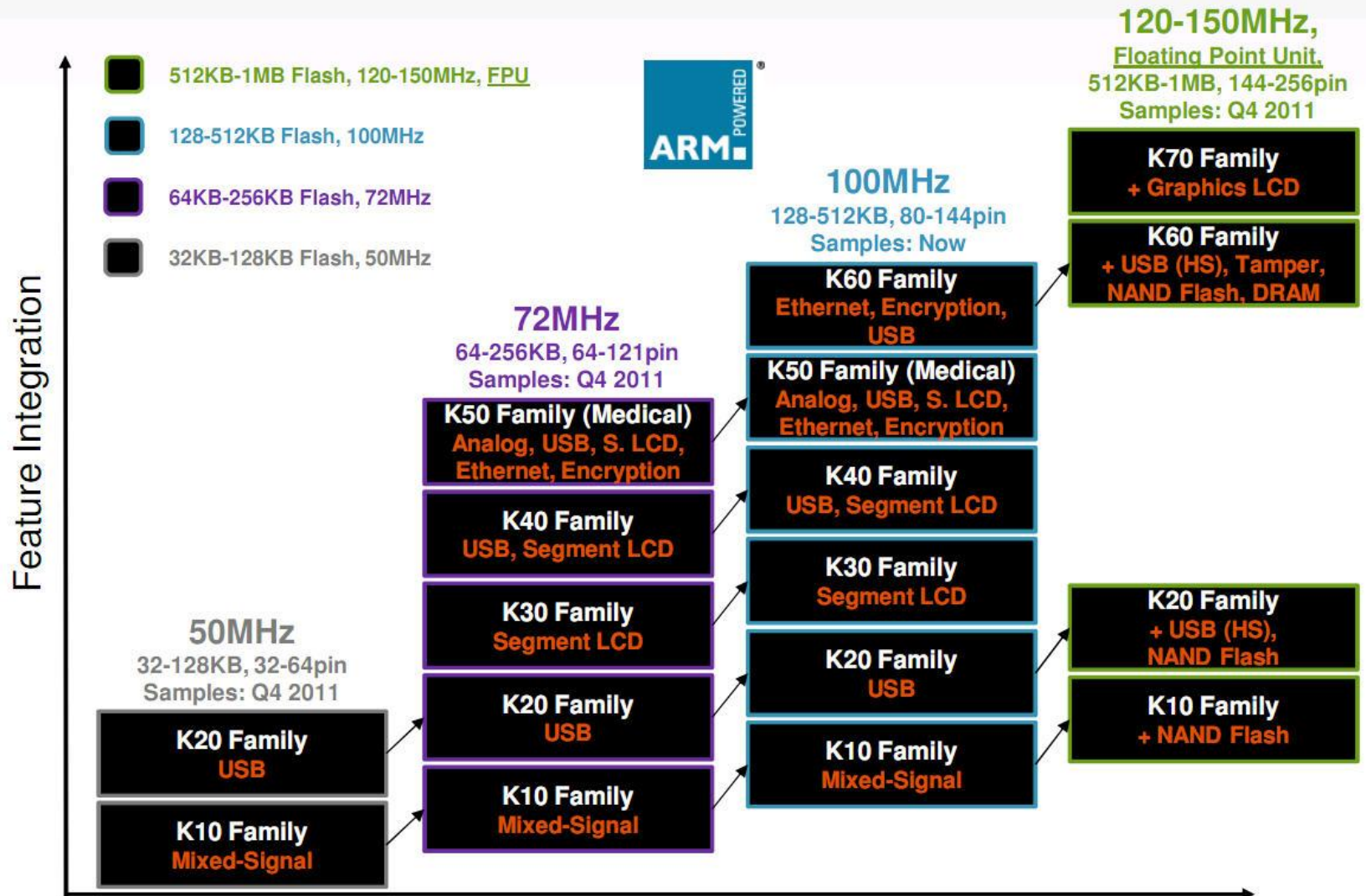
MCU Family	Features										Common System IP	Common Analog IP	Common Digital IP	Development Tools
	USB OTG (FS & HS)	Dual CAN	Ethernet (IEEE 1588)	Encryption (CAU+RNG)	LCD (Segment/Graphics)	NAND Flash Controller (120MHz, 150MHz, only)	Floating Point Unit (120MHz, 150MHz, only)	Hardware Tamper Unit	DRAM Controller (256 pin MAP/BSA only)					
K70 Family 512KB-1MB, 196-256pin	●	●	●	●	●	●	●	●	●	●	32-bit ARM Cortex-M4 Core w/ DSP Instructions Next Generation Flash Memory High Reliability, Fast Access FlexMemory w/ EEPROM capability SRAM Memory Protection Unit Low Voltage, Low Power Multiple Operating Modes, Clock Gating (1.71V-3.6V with 5V tolerant I/O) DMA -40 to 105C	16-bit ADC	CRC	Bundled IDE w/ Processor Expert
K60 Family 256KB-1MB, 100-256pin	●	●	●	●		●	●	●	●	Programmable Gain Amplifiers			I ² C	
K50 Family 128-512KB, 64-144pin	●		●	●	●							12-bit DAC	SAI (I ² S)	Modular Tower H/ware Development System
K40 Family 64-512KB, 64-144pin	●	●			●					High-speed Comparators			UART/SPI	
K30 Family 64-512KB, 64-144pin		●			●							Low-power Touch Sensing	Programmable Delay Block	Broad 3rd party ecosystem
K20 Family 32KB-1MB, 32-144pin	●	●				●	●			RTC			External Bus Interface	
K10 Family 32KB-1MB, 32-144pin		●				●	●					eSDHC		

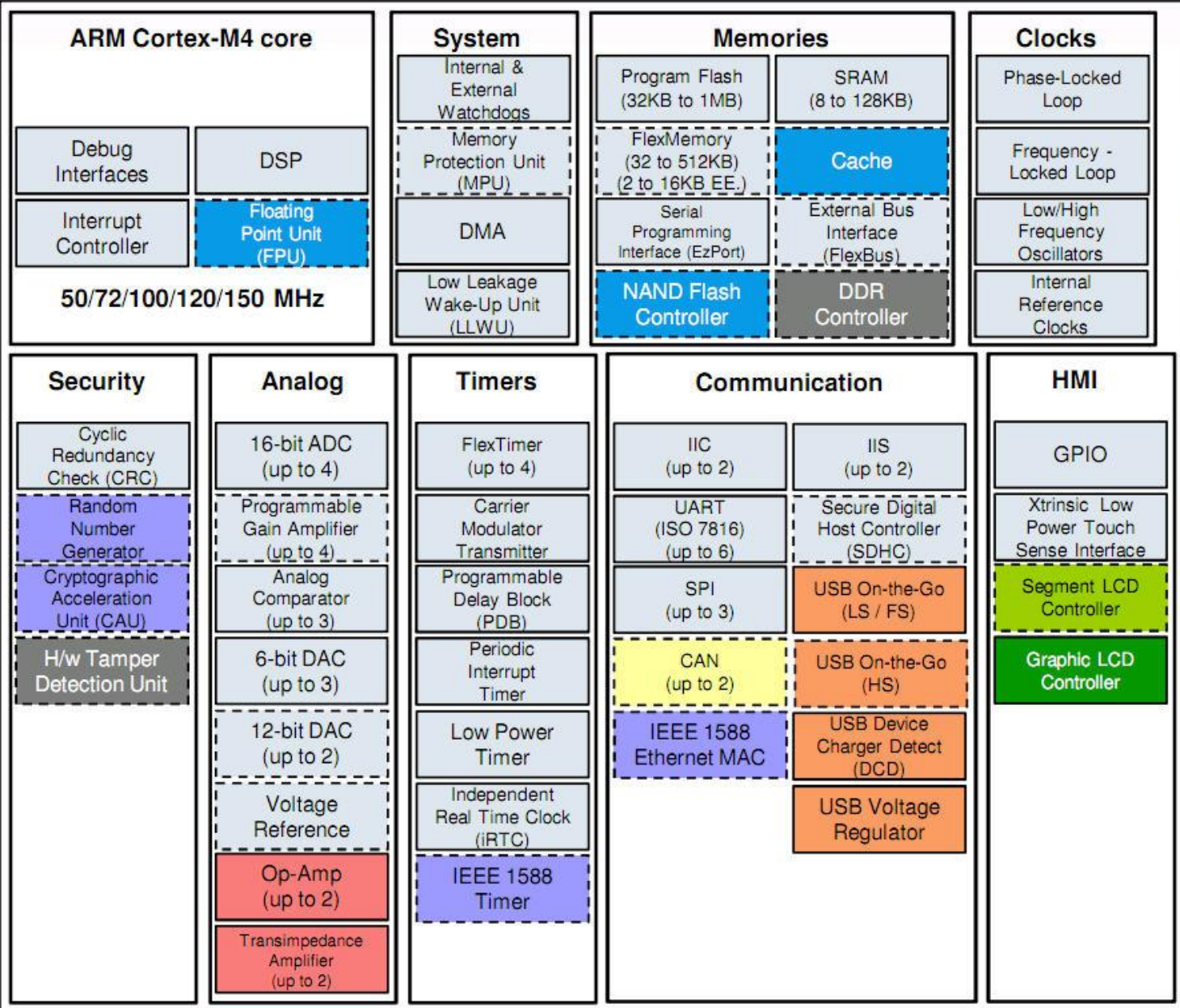
Available Q4 2010



Kinetis 系列

Kinetis: Scalable MCUs based on the ARM® Cortex™-M4 core





Kinetis: Package Options



81MAPBGA
8 x 8 mm
0.65mm pitch

104MAPBGA
8 x 8 mm
0.65mm pitch

121MAPBGA
8 x 8 mm
0.65mm pitch

144MAPBGA
13 x 13 mm
1.0mm pitch

196MAPBGA
15 x 15 mm
1.0mm pitch

256MAPBGA
17 x 17 mm
1.0mm pitch

(K10/20/30/40/50)

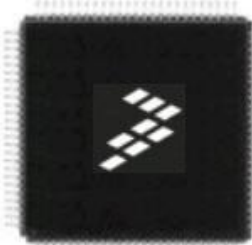
(K10/20/30/40/50)

(K10/20/30/40/50/60)

(K10/20/30/40/50/60)

(K60/70)

(K60/70)



48LQFP

64LQFP

80LQFP

100LQFP

144LQFP

7 x 7 mm

10 x 10 mm

12 x 12 mm

14 x 14 mm

20 x 20 mm

0.55mm pitch

0.5mm pitch

0.5mm pitch

0.5mm pitch

0.5mm pitch

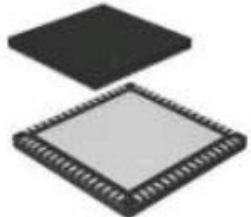
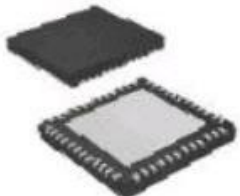
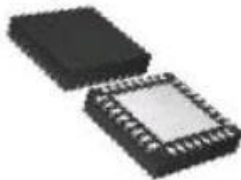
(K10/20)

(K10/20/30/40/50)

(K10/20/30/40/50)

(K10/20/30/40/50/60)

(K10/20/30/40/50/60)



32QFN

48QFN

64LQFN

5 x 5 mm

7 x 7 mm

9 x 9 mm

0.5mm pitch

0.5mm pitch

0.5mm pitch

(K10/20)

(K10/20)

(K10/20/30/40/50)



ARM Cortex-M4 from Freescale

▶ 向下兼容ARM Cortex-M3

▶ 新特性

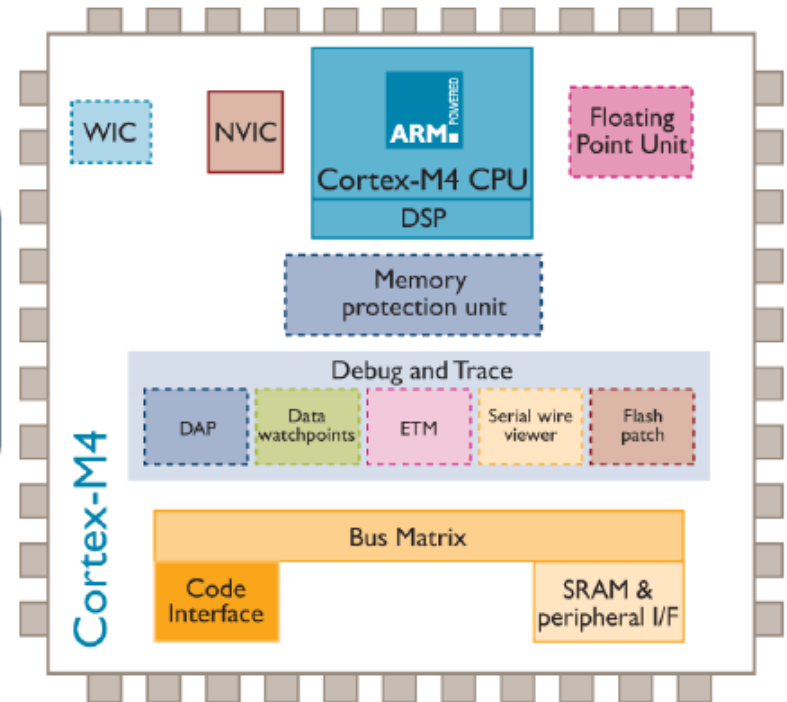
- 单周期MAC (最高支持32 x 32，结果为32-bit)
- DSP扩展
- 单精度浮点处理单元

▶ 飞思卡尔IP和创新

- 片内指令和数据缓存
- 交换机可用于并发访问多个主设备/从设备
- 片内DMA用于降低CPU负载
- Low-leakage唤醒单元为低功耗操作增加了便利

▶ 为数字信号处理而构建

- 电机控制 – 高级算法, 长寿命, 电源效率
- 自动控制 – 以较低成本实现高带宽的计算和算法
- 电源管理 – 为低功耗或电池供电系统而设计
- 音频和视频 – 提升5倍软件性能，提高电池续航能力



PKH	QADD	QADD16	QADD8	QASX	QDADD	QDSUB	QSAX	QSUB
QSUB16	QSUB8	SADD16	SADD8	SASX	SEL	SHADD16	SHADD8	SHASX
SHSAX	SHSUB16	SHSUB8	SMLABB	SMLABT	SMLATB	SMLATT	SMLAD	SMLALBB

ADC	ADD	ADR	AND	ASR	B	CLZ
BFC	BFI	BIC	CDP	CLREX	CBNZ	CBZ
CMP				DBG	EOR	LDC
LDMIA	BKPT	BLX	ADC	ADD	ADR	LDMDB
LDRBT	BX	CPS	AND	ASR	B	LDR
LDREXH	DMB		BL	BIC		LDRB
LDRSBT	DSB	CMN	CMP	EOR		LDRD
MCR	ISB	LDR	LDRB	LDM		LDREX
MCRR	MRS	LDRH	LDRSB	LDRSH		LDREXB
MRC	MSR	LSL	LSR	MOV		LDRH
NOP	NOP	REV	MUL	MVN	ORR	LDRHT
PLDW	REV16	REVSH	POP	PUSH	ROR	LDRSH
RBIT	SEV	SXTB	RSB	SBC	STM	LDRSB
ROR	SXTH	UXTB	STR	STRB	STRH	LDRSHT
SBFX	UXTH	WFE	SUB	SVC	TST	LDRSH
SMULL	WFI	YIELD				LDRSH
STMDB						LDRSH
STRD	STREX	STREXB	STREXH	STR	STRB	STRB
SUB	SXTB	SXTH	TBB	STRH	STRHT	STRB
UBFX	UDIV	UMLAL	UMULL	STRH	STRHT	STRB
WFE	WFI	YIELD	IT	STRH	STRHT	STRB

CORTEX-M0/M1

CORTEX-M3

SMLALB1	SMLALTB
SMLALTT	SMLALD
SMLAWB	SMLAWT
SMLSD	SMLSLD
SMMLA	SMMLS
SMMUL	SMUAD
SMULBB	SMULBT
SMULTB	SMULTT
SMULWB	SMULWT
SMUSD	SSAT16
SSAX	SSUB16
SSUB8	SXTAB
SXTAB16	SXTAH
SXTB16	UADD16
UADD8	UASX
UHADD16	UHADD8
UHASX	UHSAX
UHSUB16	UHSUB8
UMAAL	UQADD16
UQADD8	UQASX
UQSAX	UQSUB16
UQSUB8	USAD8
USADA8	USAT16

USAX	USUB16	USUB8	UXTAB	UXTAB16	UXTAH	UXTB16
------	--------	-------	-------	---------	-------	--------

Cortex-M4

VABS	VADD	VCMP	VCMPPE	VCVT	VCVTR	VDIV	VLDM	VLDR
VMLA	VMLS	VMOV	VMRS	VMSR	VMUL	VNEG	VNMLA	VNMLS
VNMUL	VPOP	VPUSH	VSQRT	VSTM	VSTR	VSUB		

Cortex-M4F

ARM Cortex-M4 from Freescale

➤ 16-bit逐次逼近ADC

- 1.15V 最小参考电压
- 差分或单端
- 1, 4, 8, 16或32次平均
- 自动比较功能
- 与DAC同步触发
- 可配置的精度, 采样时间、采样速度和功耗 (8/10/12/16位精度)
- 每个ADC转换器最高支持20个通道

➤ 参考电压 (Vref)

- 可校准
- $< 33\text{ppm}/^{\circ}\text{C}$ 温度变化(0° - 50° C 温度范围)

➤ 12-bit DAC

- 16字DAC FIFO
- 硬件或软件触发

➤ 高速比较器

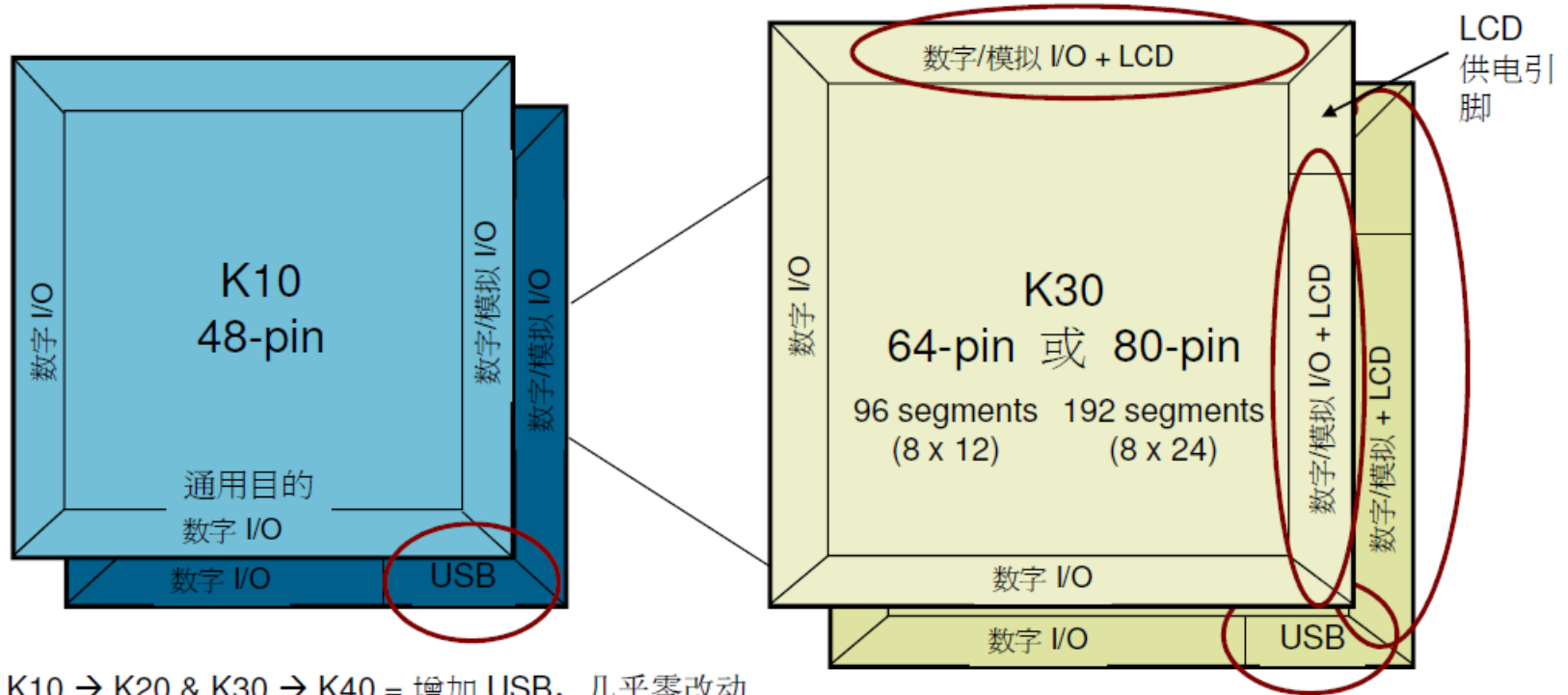
- 可编程迟滞控制和中断触发
- 可选择的比较输出反转
- 集成6-bit参考DAC

➤ 可编程增益放大器

- 64倍放大



Pin Compatibility Across Families



K10 → K20 & K30 → K40 = 增加 USB, 几乎零改动

✓唯一的区别是增加4个USB引脚和减少4个数字I/O引脚

K10 → K30 & K20 → K40 = 增加段码式LCD, 最小的布板改动

✓数字和模拟 I/O 信号保持不变

✓段码式LCD信号与现有的数字模拟 I/O 信号复用

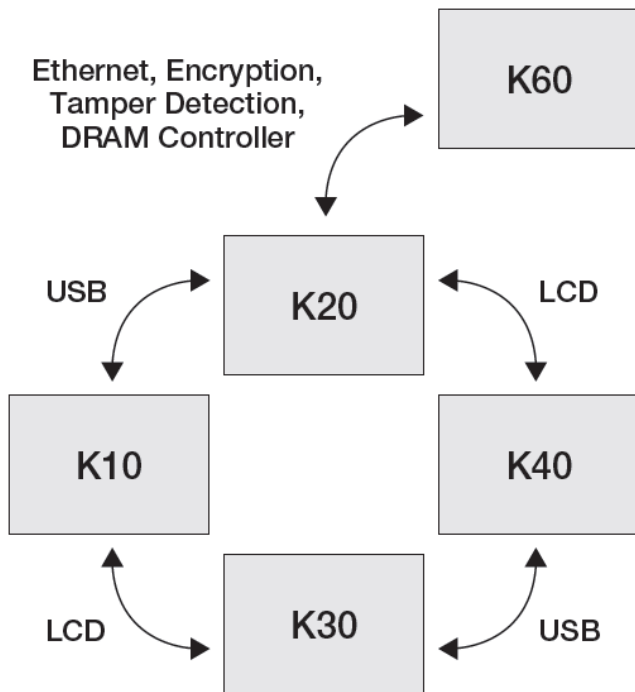
✓大多数数字 I/O 信号与段码式LCD信号复用 可通过大封装增加引脚

K20 → K60 = 增加以太网引脚, 而无任何改动

✓所有以太网信号与现有的数字模拟I/O信号复用



Pin Compatibility Across Families



Type	Body Size	Pitch	Families
32-pin QFN	5 x 5 mm	0.5 mm	K10, K20
48-pin QFN	7 x 7 mm	0.5 mm	K10, K20
48-pin LQFP	7 x 7 mm	0.5 mm	K10, K20
64-pin QFN	9 x 9 mm	0.5 mm	K10, K20, K30, K40
64-pin LQFP	10 x 10 mm	0.5 mm	K10, K20, K30, K40
80-pin LQFP	12 x 12 mm	0.5 mm	K10, K20, K30, K40
81-pin MAPBGA	8 x 8 mm	0.65 mm	K10, K20, K30, K40
100-pin LQFP	14 x 14 mm	0.5 mm	K10, K20, K30, K40, K60
104-pin MAPBGA	8 x 8 mm	0.65 mm	K10, K20, K30, K40, K60
144-pin LQFP	20 x 20 mm	0.5 mm	K10, K20, K30, K40, K60
144-pin MAPBGA	13 x 13 mm	1.0 mm	K10, K20, K30, K40, K60
196-pin MAPBGA	15 x 15 mm	1.0 mm	K60
256-pin MAPBGA	17 x 17 mm	1.0 mm	K60



Memory Map of Kinetis Families

With FlexMemory

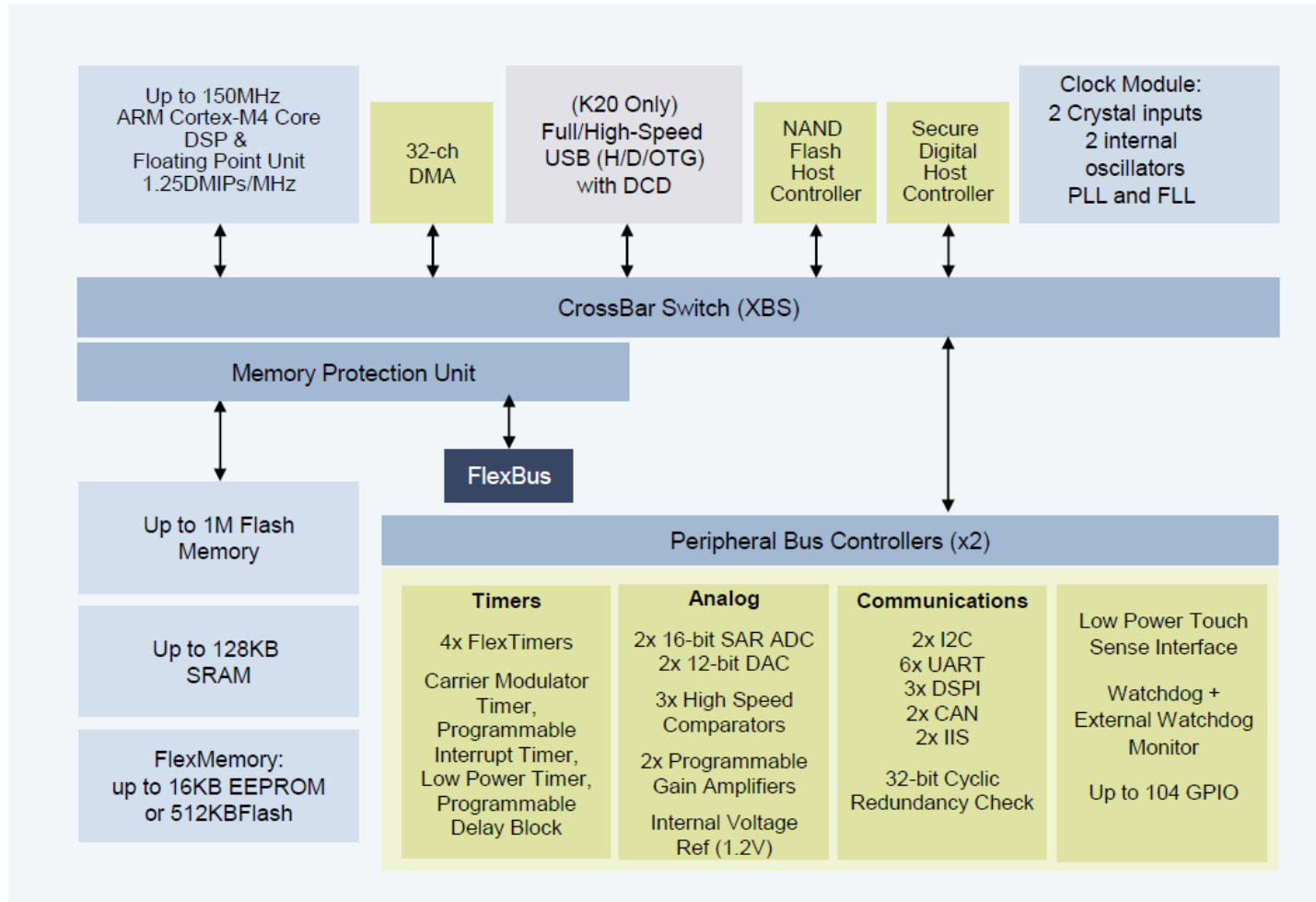
0x0000_0000	PFlash	256KB
0x0004_0000	Reserved	
0x1000_0000	FlexNVM	256KB
0x1004_0000	Reserved	
0x1400_0000	FlexRAM	4KB
0x1400_1000	Reserved	
0x1FFF_0000	System RAM TCML	64KB
0x2000_0000	System RAM TCMU	64KB
0x2001_0000	Reserved	
0x2200_0000	TCMU Bitband Alias	2MB
0x2220_0000	Reserved	
0x4000_0000	AIPS0 Peripherals	512KB
0x4008_0000	AIPS1 Peripherals	512KB
0x400F_F000	GPIO Peripheral	4KB
0x4010_0000	Reserved	
0x4200_0000	Periph Bitband Alias	32MB
0x4400_0000	Reserved	
0x6000_0000	Flexbus	2GB
0xE000_0000	Private Peripheral	1MB
0xE010_0000	Reserved	
0xFFFF_FFFF	Reserved	

Without FlexMemory

0x0000_0000	PFlash	512KB
0x0008_0000	Reserved	
0x1400_0000	FlexRAM	4KB
0x1400_1000	Reserved	
0x1FFF_0000	System RAM TCML	64KB
0x2000_0000	System RAM TCMU	64KB
0x2001_0000	Reserved	
0x2200_0000	TCMU Bitband Alias	2MB
0x2220_0000	Reserved	
0x4000_0000	AIPS0 Peripherals	512KB
0x4008_0000	AIPS1 Peripherals	512KB
0x400F_F000	GPIO Peripheral	4KB
0x4010_0000	Reserved	
0x4200_0000	Periph Bitband Alias	32MB
0x4400_0000	Reserved	
0x6000_0000	Flexbus	2GB
0xE000_0000	Private Peripheral	1MB
0xE010_0000	Reserved	
0xFFFF_FFFF	Reserved	



The K10 Family Block Diagram

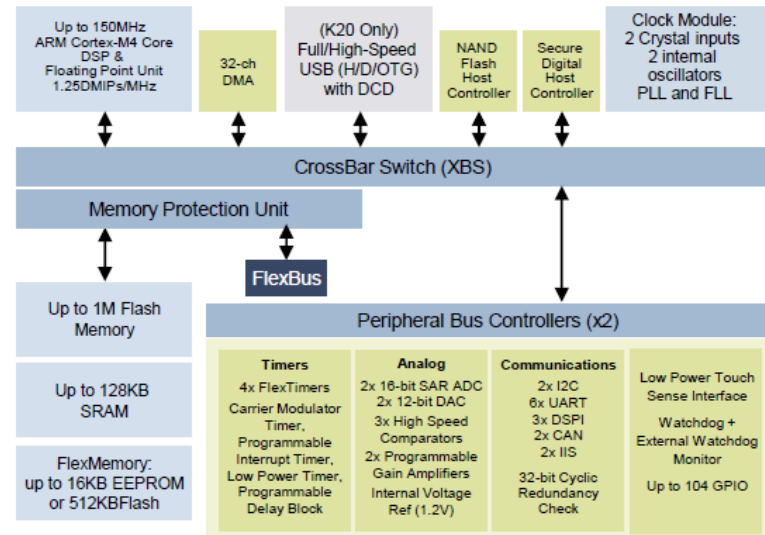


The K10 Family Overview

High Integration Mixed-Signal MCUs

- ▶ **Processing Performance and FlexMemory**
 - Direct Memory Access, Cross Bar Switch, and on-chip Cache maximize bus bandwidth and Flash execution
 - FlexMemory provides on-chip, high-endurance configurable EEPROM and/or additional Flash memory
- ▶ **(K20 Only) Connect via USB AND charge a battery**
 - USB 2.0 Full-Speed Device/Host/OTG Controller with integrated transceiver, HS via ULPI interface
 - Includes Device Charge Detector (DCD) and Regulator to supports battery charging via USB for Portable Devices
- ▶ **Flexible and Powerful Mixed Signal Capability**
 - 16-bit ADC enables small signal capture for medical/sensing applications, or high speed conversions for motor control.
 - 12-bit DAC, High-Speed Comparator, and Voltage Reference on-chip reduces system cost
- ▶ **Ultra-low power with 1.71V operation**
 - Multiple low power modes and Flash & analog operation down to 1.71V – power profile optimization and prolonged battery life
 - Stop Currents <500nA, run currents <200uA/MHz

**32KB Flash in 32 pin package
starting at \$0.99 for 10K SRP**



Enablement Bundle

TOWER development system
Complementary MQX RTOS with USB Stack
Eclipse-Based CodeWarrior 10.0 IDE
Processor Expert Rapid Application Development Tool
IAR, Keil and full ARM Ecosystem Support
Motor Control and DSP Libraries

Family	USB OTG + DCD
K10	-
K20	X



K10 主要性能

- Voltage range: 1.71 to 3.6 V , 5 V tolerant GPIO
- Up to 100 MHz(120 MHz) with DSP , instructions ~1.25 Dhrystone MIPS /MHz
- 32~1MB flash/8K~128 KB RAM
- 16-bit ADCs, 12-bit DACs, 增益可编程放大器,电容式触摸键盘接口
- UARTs with ISO7816 and IrDA support, I2S, CAN, I2C and DSPI , Modulator Transmitter for IR waveform generation
- Powerful Flex Timers which support general purpose, PWM, and motor control functions
- Timer for RTOS ,
- temperature ranges from -40 °C to 105 °C



K10 系列可选

引脚: 32/48/64/80/100/104/121/144

K10 Family Options

Part Number	Memory					Features									Packages												
	CPU (MHz)	Flash (KB)	Flex NVM (KB)	SRAM (KB)	Cache (KB)	Single Precision Floating Point Unit	Memory Protection	CAN	Secure Digital Host	NAND Flash Controller	External Bus Interface	12-bit DAC	Prog. Gain Amplifier	5V Tolerant I/O	FM	FT	LF	EX	LH	LK	MB	LL	ML	MC	LQ	MD	
															32 QFN (5x5)	48QFN (7X7)	48LQFP (7X7)	64QFN (9X9)	64LQFP (10X10)	80LQFP (12X12)	81BGA (8X8)	100LQFP (14X14)	104BGA (8X8)	121BGA (8x8)	144LQFP (20x20)	144BGA (13x13)	
MK10DN32Vyy5	50	32		8											√	√	√	√	√								
MK10DN64Vyy5	50	64		16											√	√	√	√	√								
MK10DN128Vyy5	50	128		16											√	√	√	√	√								
MK10DN512Vw10	100	512		128																√	√	√	√	√	√	√	√
MK10FN1M0Vyy12	120	1 MB		128	16	√	√	√	√	√	√	√	√	√											√	√	
MK10DX32Vyy5	50	32	32	8											√	√	√	√	√								
MK10DX64Vyy5	50	64	32	16											√	√	√	√	√								
MK10DX128Vyy5	50	128	32	16											√	√	√	√	√								
MK10DX64Vyy7	72	64	32	16				√		√	√	√	√				√	√	√	√	√						
MK10DX128Vyy7	72	128	32	32				√		√	√	√	√				√	√	√	√	√	√	√				
MK10DX256Vyy7	72	256	32	64				√		√	√	√	√				√	√	√	√	√	√	√				
MK10DX128Vyy10	100	128	128	32				√	√	√	√	√	√												√	√	
MK10DX256Vyy10	100	256	256	64				√	√	√	√	√	√												√	√	
MK10FX512Vyy12	120	512	512	128	16	√	√	√	√	√	√	√	√												√	√	



Motor Control Use Case

DSP hardware:

▶ Accelerates motor control calculations

DMA:

▶ Off loads CPU from repetitive data transfers

16-bit ADC & PGA:

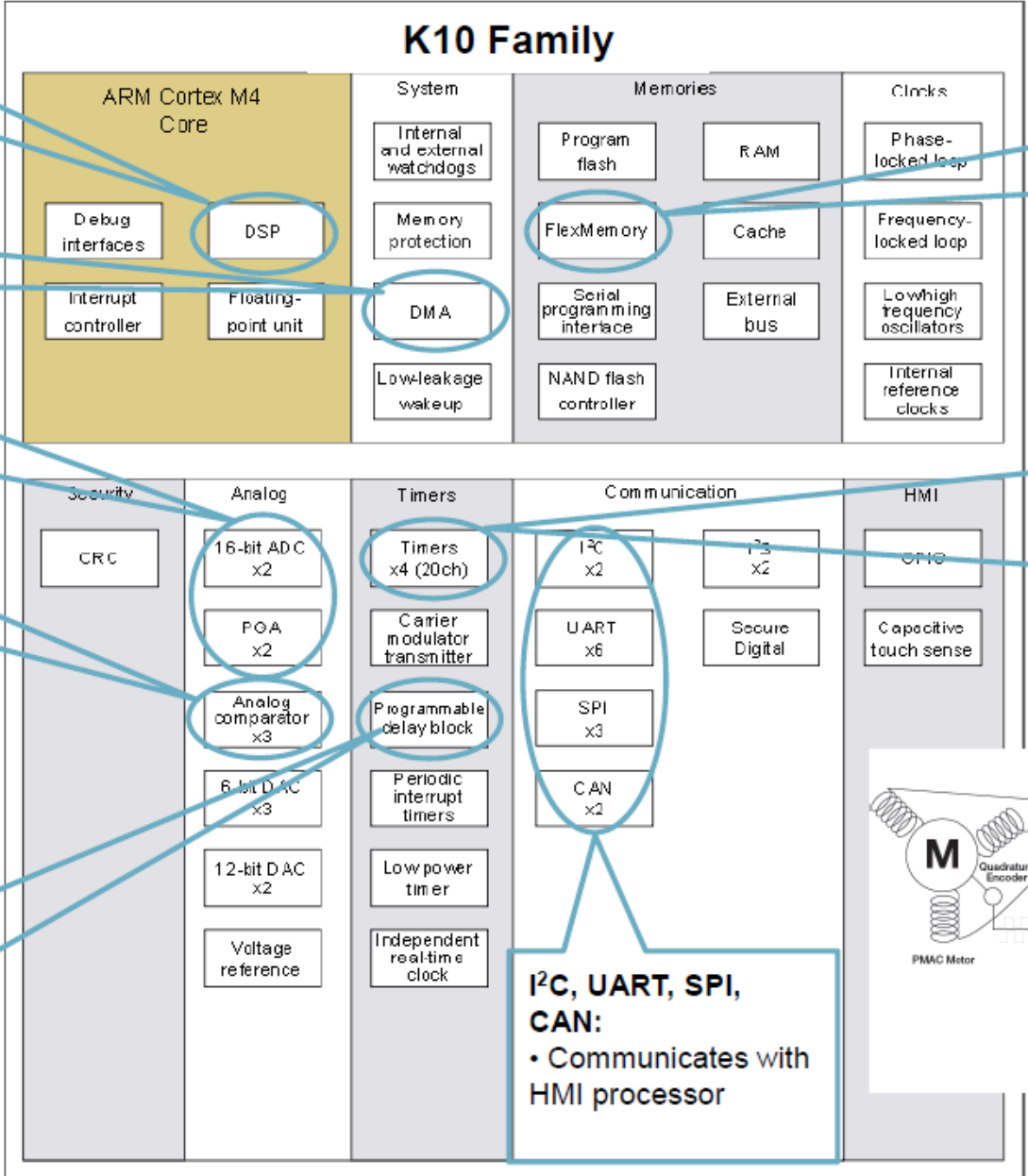
▶ Measures 3 phase bridge current and voltage

Analog Comparator:

▶ Detects back EMF
▶ Monitors over current

Programmable delay block:

▶ Schedules delayed ADC conversions relative to Timer triggers



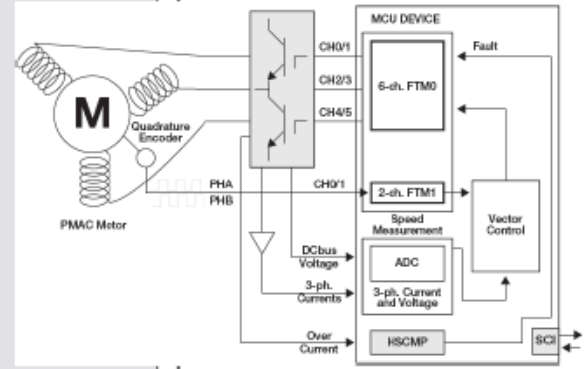
FlexMemory:

▶ Saving motor calibration data
• Remote update bootloader

Timers:

▶ Drives various motor types including stepper, BLDC, and PMAC motors with sensor or sensorless algorithms
▶ Built-in quadrature decoder detects motor speed

I²C, UART, SPI, CAN:
• Communicates with HMI processor



100 Pin K10LL 的I/O

■ ~ 70个I/O端口 (GPIO)

- TSI 16
- ADC 16
- DAC 1
- ACP 3
- PWM 8
- UART 4
- I2C 2
- I2S 1
- SPI 3
- CAN 2



16-bit ADC

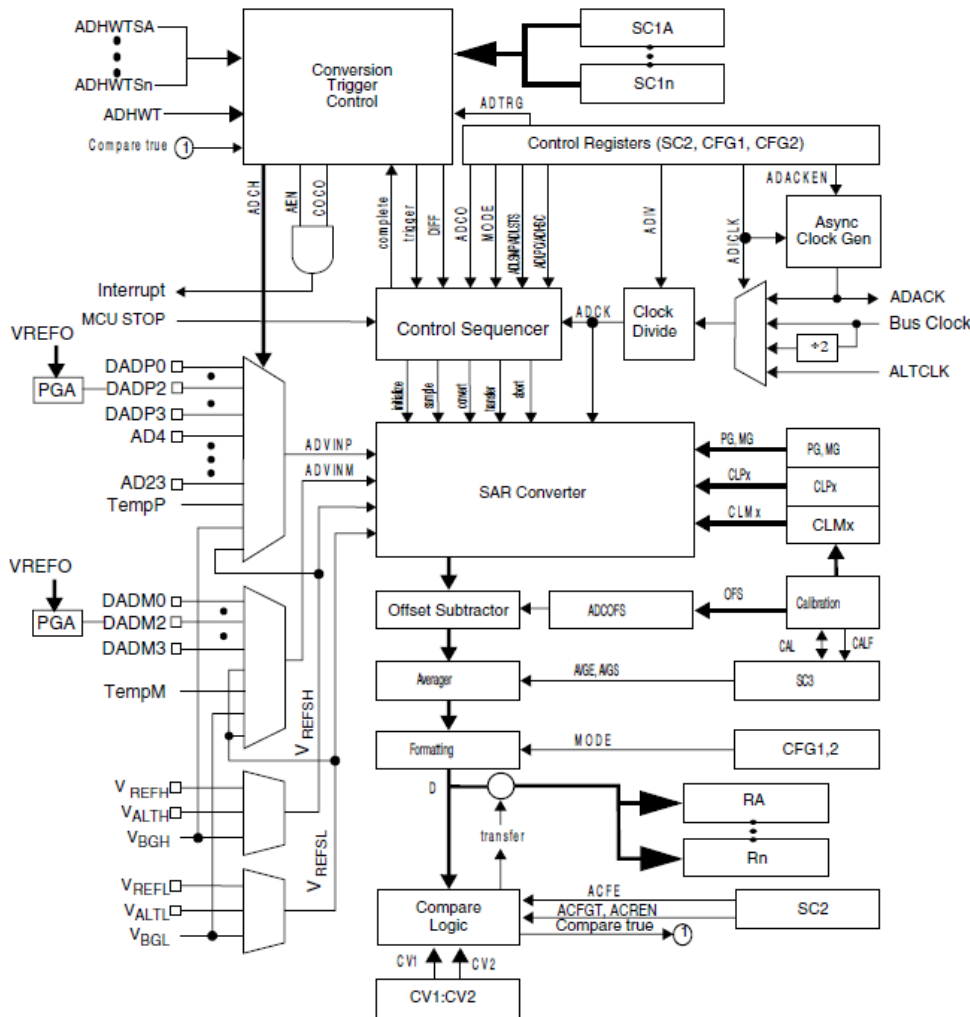
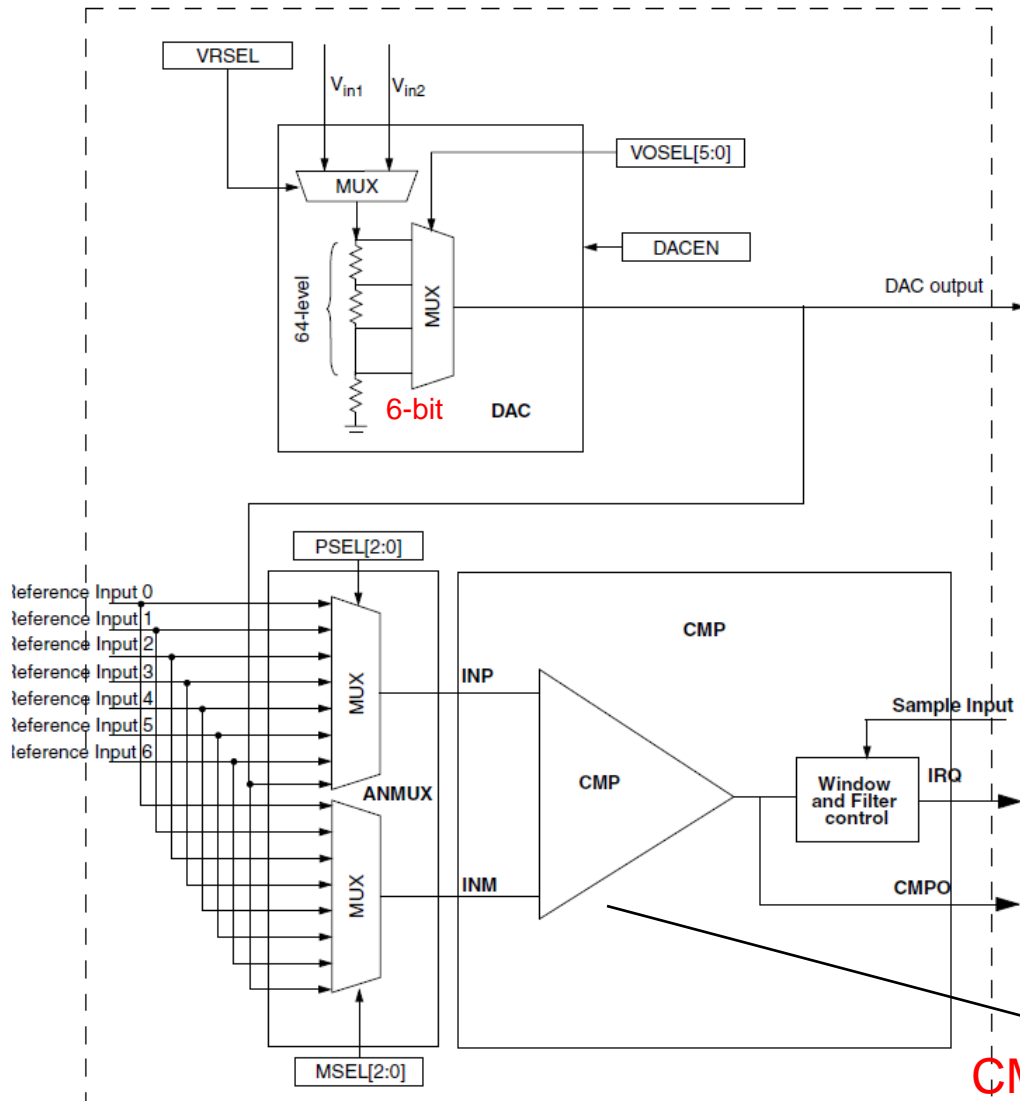


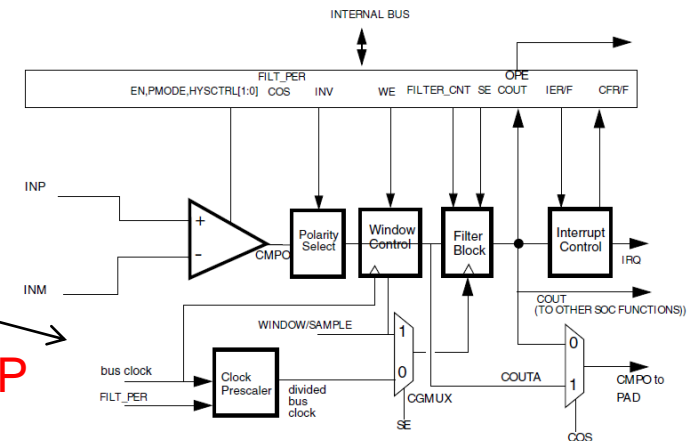
Figure 34-1. ADC block diagram

- ✓ Up to **4 pairs of differential** and 24 single-ended external analog inputs
- ✓ Output modes:
 - differential 16-bit, 13-bit, 11-bit or 9-bit
 - single-ended 16-bit, 12-bit, 10-bit and 8-bit
- ✓ **Programmable Gain Amplifier (PGA)** : up to **x64** gain
 - Amplify low-amplitude signals before they are fed to ADC
 - Only work with differential input (range from $0\sim 1.2V \pm 10\text{mV}$)
- ✓ **ADC conversion clk frequency** :
 - 1~18MHz for ≤ 13 -bit mode
 - 2~12MHz for 16-bit mode
- ✓ **ADC conversion rate**:
 - 18.484~818.33 Ksps for ≤ 13 -bit mode
 - 37.037~361.402Ksps for ≤ 13 -bit mode
 (continuous conversion, peripheral clk=50MHz, no ADC hardware averaging)
- ✓ Conversion complete / hardware average complete flag and interrupt
- ✓ Selectable hardware conversion trigger with hardware channel select
- ✓ Automatic compare with interrupt for less-than, greater-than or equal-to, within range, or out-of-range, programmable value
- ✓ Hardware average function
- ✓ Self-calibration mode

Analog Comparator



- ✓ Operates over the entire supply range
- ✓ Programmable hysteresis control
- ✓ Selectable interrupt on rising edge, falling edge, or both rising or falling edges of comparator output
- ✓ Selectable inversion on comparator output
- ✓ Comparator output may be:
 - Sampled
 - Windowed
 - Digitally Filtered
 - * Filter can be bypassed
 - * Can be clocked via external SAMPLE signal or scaled bus clock
- ✓ Support DMA transfer
 - A comparison event can be selected to trigger a DMA transfer.
- ✓ Two software selectable performance levels:
 - Shorter propagation delay at the expense of higher power $T_d = 50\text{ns}$ (typ.)
 - Low power, with longer propagation delay $T_d = 250\text{ns}$ (typ.)



Voltage Reference(VREFV1)

- ✓ Intended to supply an accurate 1.2 V voltage output.
- ✓ VREFV1 can be used in medical applications such as glucose meters to provide a reference voltage to biosensors or as a reference to analog peripherals such as the ADC, DAC, or CMP.
- ✓ Low power mode: VREFV1 can only be used for internal peripheral
High power mode: VREFV1 can be used for external peripheral, 100nF capacitor needed.

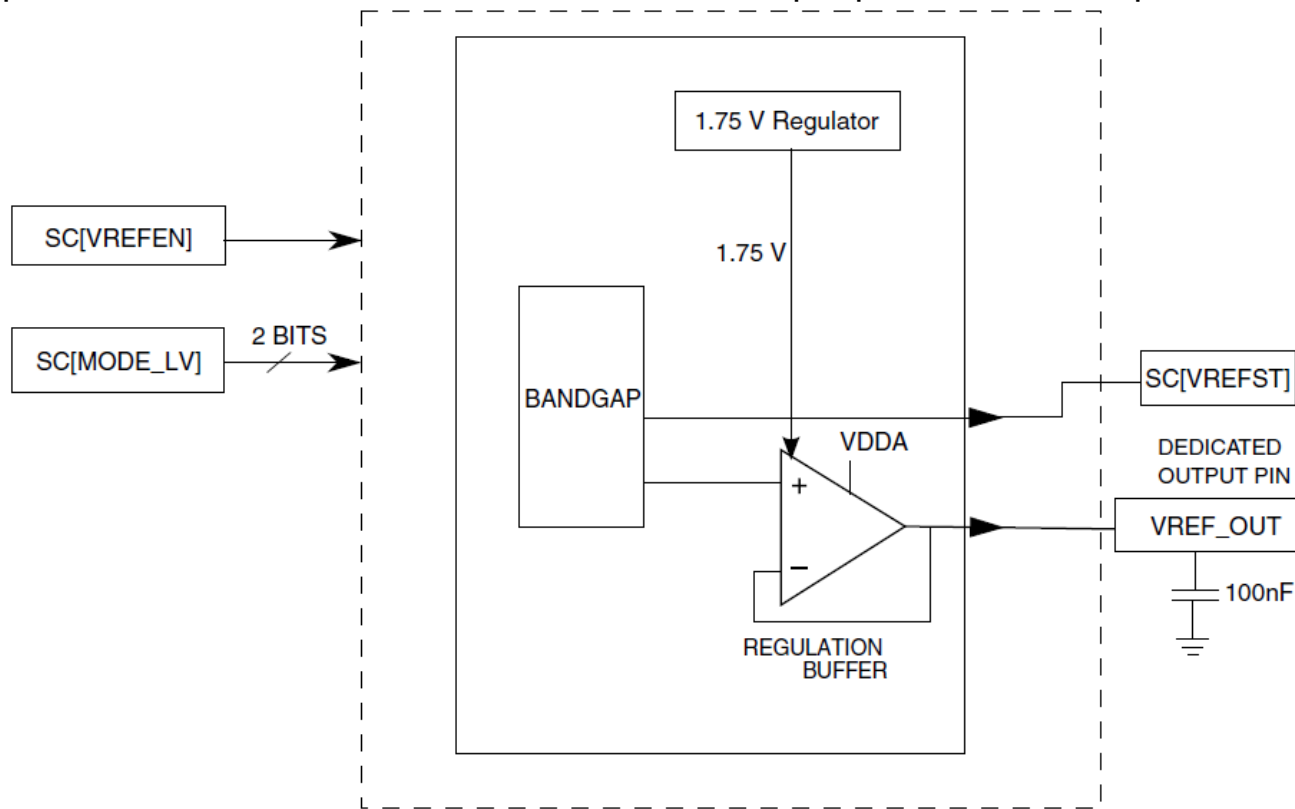


Figure 37-1. Voltage reference block diagram



USB Voltage Regulator (K20)

- ✓ The USB Voltage Regulator module is a LDO linear voltage regulator to provide 3.3V power from an input power supply varying from 2.7 V to 5.5 V.
- ✓ Low drop-out voltage: 300 mV
- ✓ Output current: 120 mA.
- ✓ Automatic current limiting if the load current is greater than 290 mA
- ✓ Small output capacitor: 2.2 uF
- ✓ Stable with aluminum, tantalum or ceramic capacitors.

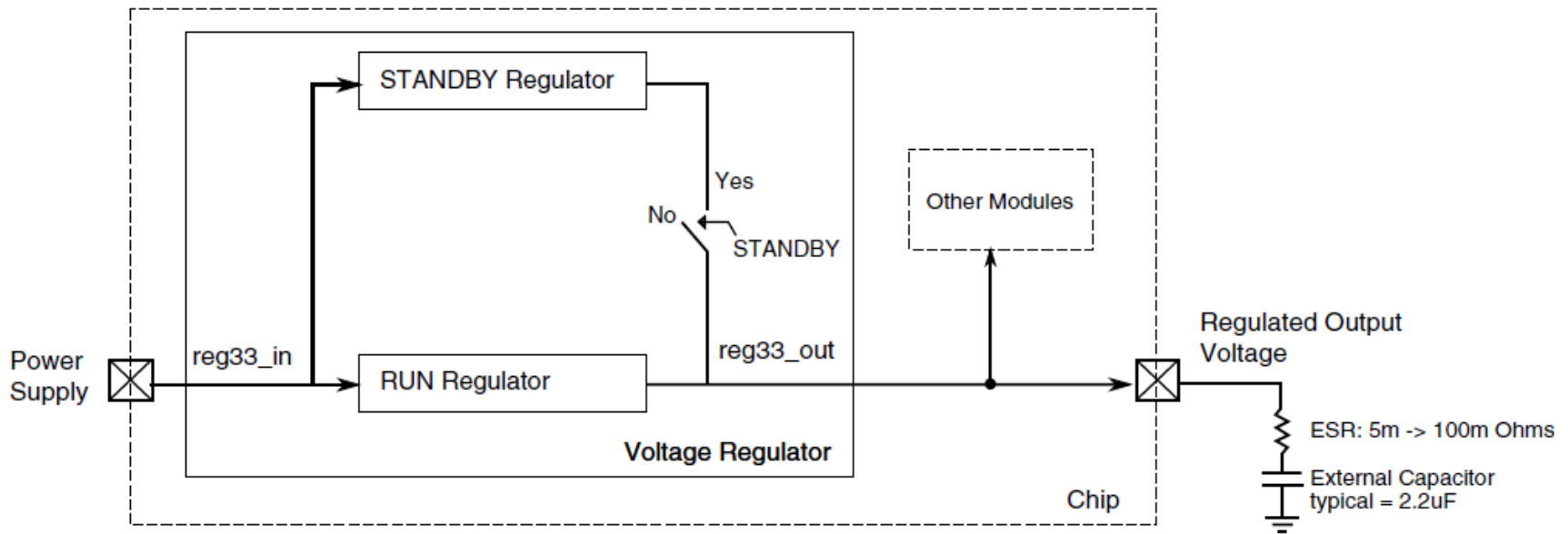
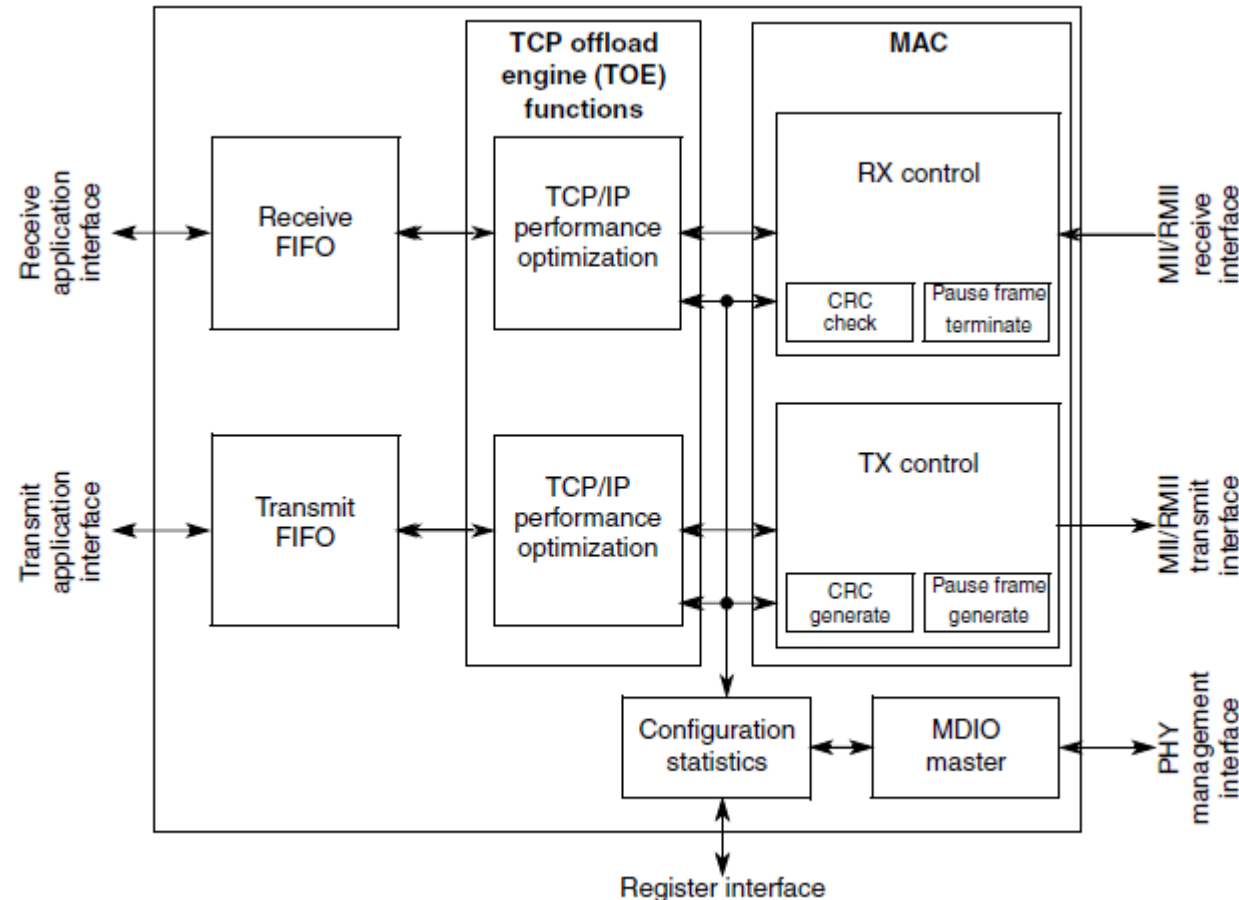


Figure 47-2. USB Voltage Regulator Block Diagram



10/100Mbps Ethernet MAC IEEE 1588 (K60)



- ✓ Implements the full 802.3 specification with preamble/SFD generation, frame padding generation, CRC generation and checking
- ✓ Dynamically configurable to support 10/100 Mbps operation
- ✓ Supports 10/100 Mbps full duplex and configurable half duplex operation
- ✓ IPv4 and IPv6 support
- ✓ Support for all IEEE 1588 frames
- ✓ Reference clock can be chosen independently of the network Speed
- ✓ Software-programmable precise time-stamping of ingress and egress frames
- ✓ 4 channel IEEE 1588 timer, each with support for input capture and output compare using the 1588 counter

Figure 44-1. 10/100 Ethernet MAC-NET Core Block Diagram

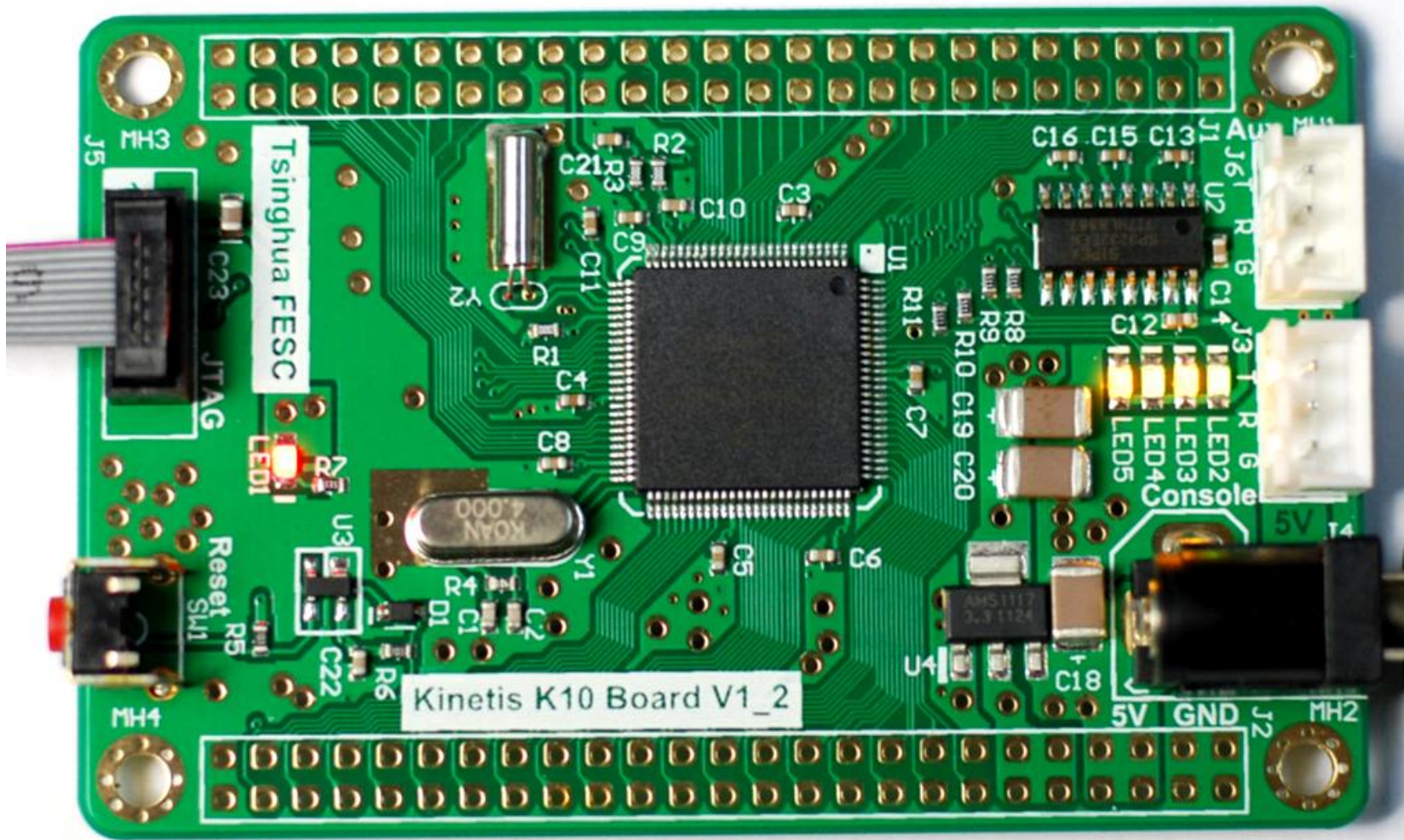


下届全国大学生Freescal杯车模竞赛 (新)

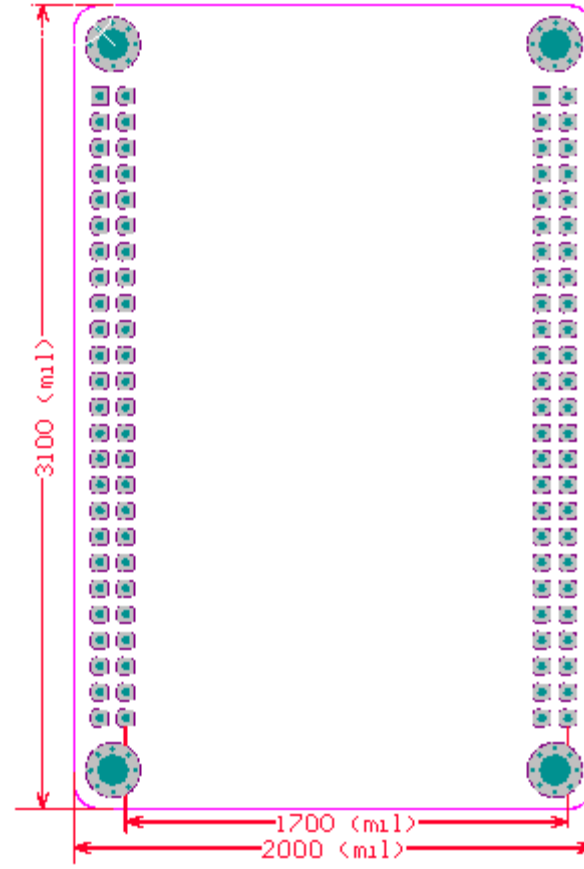
ARM Cortex-4 K10 开发套件



K10 核心小板



K10 核心小板机械尺寸



K10N512VLL100开发板J1、J2间的距离是1700mil



K10 核心小板引脚定义

J1				J2			
1	GND	2	GND	1	GND	2	GND
3	PTD0	4	PTD1	3	GND	4	GND
5	PTD2	6	PTD3	5	5V	6	5V
7	PTD4	8	PTD5	7	5V	8	5V
9	PTD6	10	PTD7	9	3.3V	10	3.3V
11	PTE0	12	PTE1	11	3.3V	12	3.3V
13	PTE2	14	PTE3	13		14	PTC18
15	PTE4	16	PTE5	15	PTC17	16	PTC16
17	PTE6	18		17	PTC15	18	PTC14
19	PTE16	20	PTE17	19	PTC13	20	PTC12
21	PTE18	22	PTE19	21	PTC11	22	PTC10
23	ADC0_DP1	24	ADC0_DM1	23	PTC9	24	PTC8
25	ADC1_DP1	26	ADC1_DM1	25	PTC7	26	PTC6
27	ADC0_DP0	28	ADC0_DM0	27	PTC5	28	PTC4
29	ADC1_DP0	30	ADC1_DM0	29	PTC3	30	PTC2
31	VDDA	32	GND	31	PTC1	32	PTC0
33	VREFH	34	GND	33	PTB23	34	PTB22
35	VREF_OUT	36	DAC0_OUT	35	PTB21	36	PTB20
37	PTE24	38	VBAT	37	PTB19	38	PTB18
39	PTE25	40	PTE26	39	PTB17	40	PTB16
41	PTA4	42	PTA5	41	PTB11	42	PTB10
43	PTA12	44	PTA13	43	PTB9	44	PTB3
45	PTA14	46	PTA15	45	PTB2	46	PTB1
47	PTA16	48	PTA17	47	PTB0	48	RESET
49	GND	50	GND	49	GND	50	GND




CodeWarrior Development Studio for Microcontrollers v10.1

► Integrated development tool suite for ColdFire, Kinetis and S08 architectures based on the Eclipse open development platform

- Project Wizard creates a new project in as few as 9 clicks
- MCU Change Wizard retargets a project to a new processor in as few as 6 clicks
- CodeWarrior optimizing C/C ++ compilers for ColdFire and Kinetis Microcontrollers included
- Extensions to Eclipse CDT to provide sophisticated features to troubleshoot and repair embedded applications
- Processor Expert combines easy-to-use component-based application creation with an expert knowledge system
- Trace and profile support for on-chip trace buffers to provide emulator-like debug capability without additional hardware
- Kernel-aware debug for MQX, Linux and OSEK
- CodeWarrior Special Edition is a complimentary version up to 128KB code size

Accelerate the development of the most complex embedded applications



Free Compiler up to 128KB!

www.freescale.com/codewarrior
to download

IAR Embedded Workbench

- ▶ The most widely used tool chain for ARM MCUs
- ▶ A consistent tool chain for ColdFire+ and Kinetis devices
- ▶ Completely integrated development environment
- ▶ Highly optimized IAR C/C++ Compiler
- ▶ Powerful IAR C-SPY Debugger
- ▶ MQX integration
- ▶ Ready-made example projects



More on www.iar.com/freescale

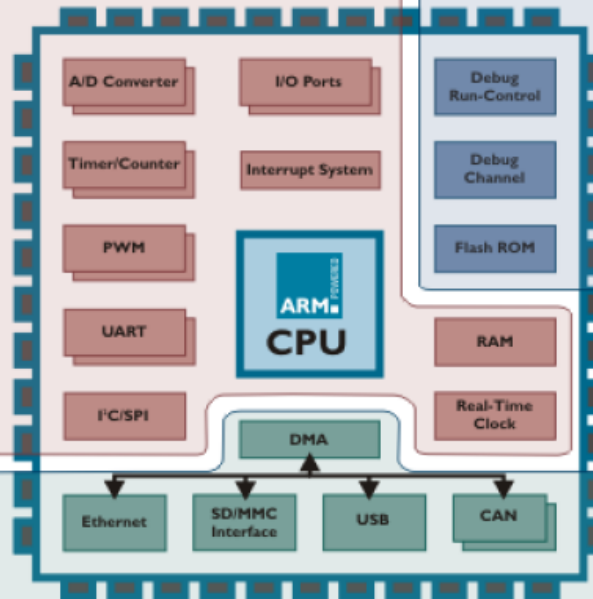
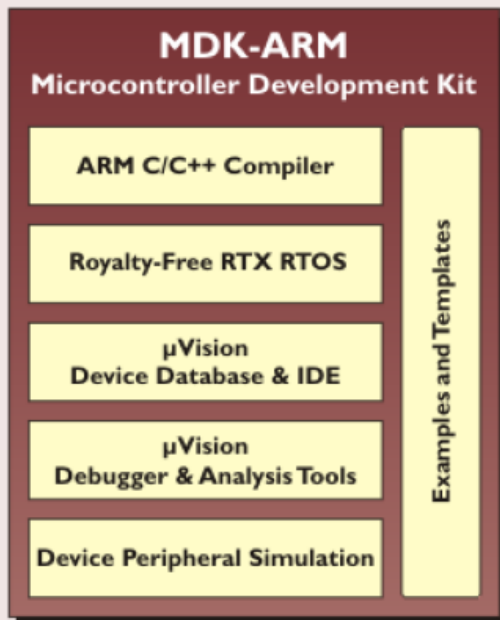
Keil Software Development Tools

Microcontroller Development Kit



Complete software development environment for Cortex-M and ARM7/9 microcontrollers

Easy to learn and use, yet powerful enough for the most demanding embedded ARM application



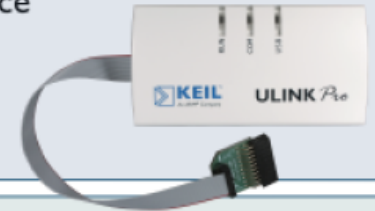
RTX and Real-Time Library

Fully featured real-time kernel

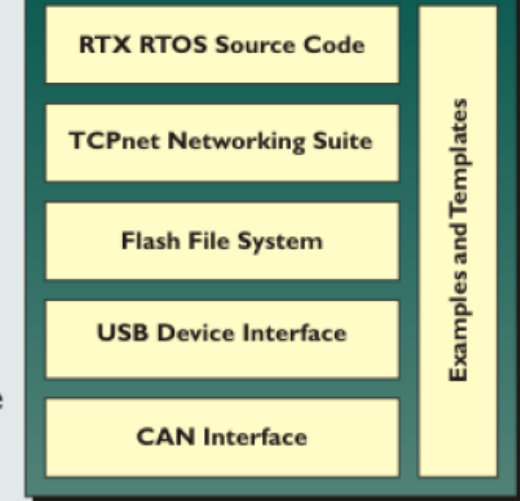
Library of middleware components to speed up software development and solve real-time and communication challenges

ULINK USB Adapters

On-the-fly debugging and Flash programming via JTAG or serial interface



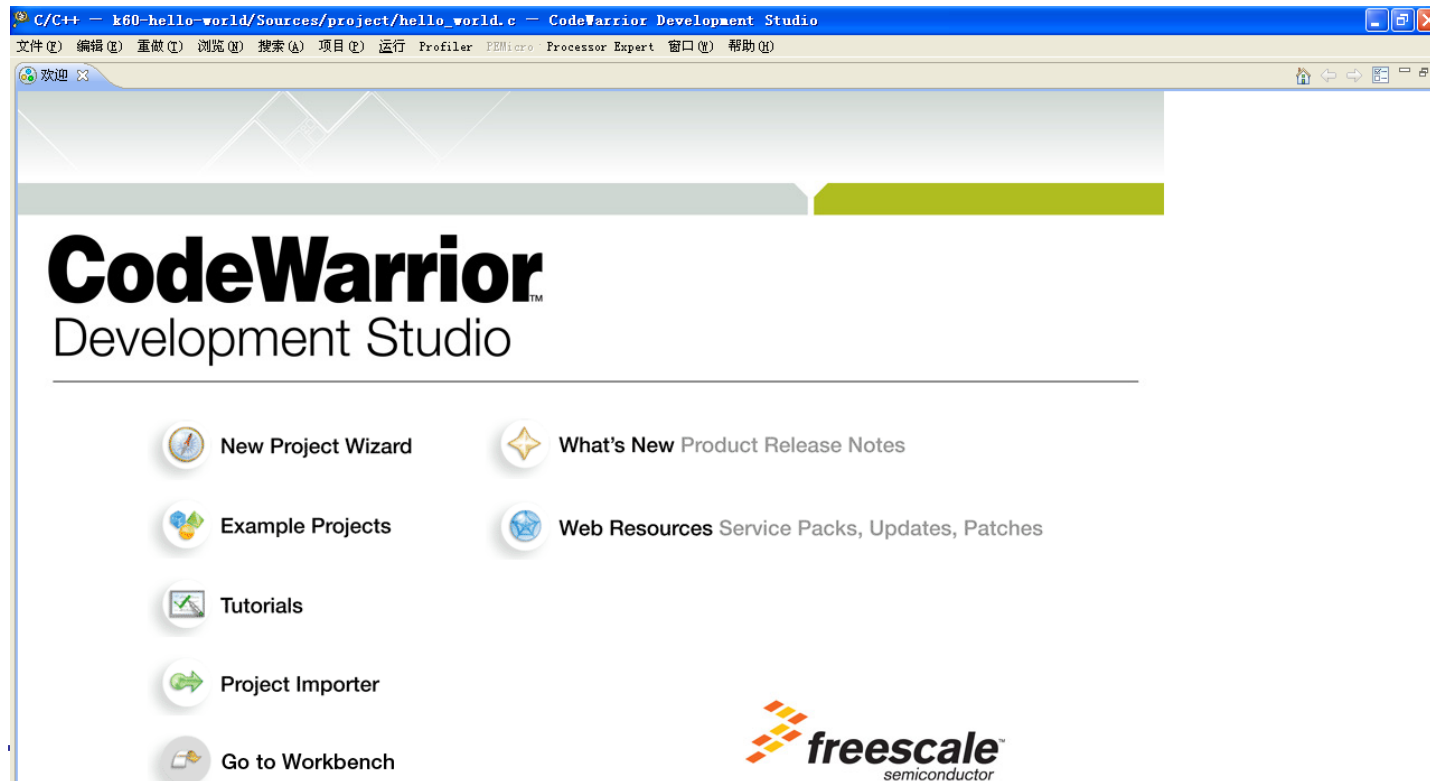
RL-ARM Real-Time Library



Codewarrior v10.x

What's New?

- ✓ **New Look!!** --based on the Eclipse open development platform user interface is substantially different from the *classic CodeWarrior IDE*
- ✓ **Support** : RS08, HCS08, ColdFire, ColdFire+, Kinetis and MPC56xx
No S12 -_-



Codewarrior v10.x

The screenshot displays the CodeWarrior Development Studio interface. The main window shows the source code for `hello_world.c`. The code is a mix of assembly and C, defining startup routines for a Kinetis microcontroller. The assembly part initializes registers `r0` through `r12` and unmask interrupts. The C part is a simple `start` function that calls the C code.

Annotations in the image provide the following instructions:

- Debug:** Choose configuration OSJTAG or U-Multilink or Jlink
- Build project:** !! Choose configuration first!! Internal_flash or Internal_RAM

The task console at the bottom shows a task named `AutoFlash` under the `Root` directory.

```
/*
 * File:      cw_crt0.s
 * Purpose:   Lowest level routines for Kinetis
 * Notes:     This is a CodeWarrior specific version of crt0.s
 */

.extern start

.global startup
.global __startup

.text

startup:
__startup:
    MOV    r0,#0           // Initialize the GPRs
    MOV    r1,#0
    MOV    r2,#0
    MOV    r3,#0
    MOV    r4,#0
    MOV    r5,#0
    MOV    r6,#0
    MOV    r7,#0
    MOV    r8,#0
    MOV    r9,#0
    MOV    r10,#0
    MOV    r11,#0
    MOV    r12,#0
    CPSIE i                // Unmask interrupts
    BL     start           // call the C code

done:
    B     done

.end
```



Learning Ref.

I. Start with K10 :

- ✓ *K10PB*: **K10 Family Product Brief**
- ✓ *K10P100M100SF2*: mainly about electrical or timing specification
- ✓ *K10P100M100SF2RM*: **datasheet**
- ✓ *K10_KQRUG*: **quick start guide**
- ✓ *KINETIS512_SC*: **demo code**
- ✓ *CW_MCU_v10_1_Examples*: **demo code**

II. Start with Codewarrior v10.x : *CW_MCU_10.1_UM*

